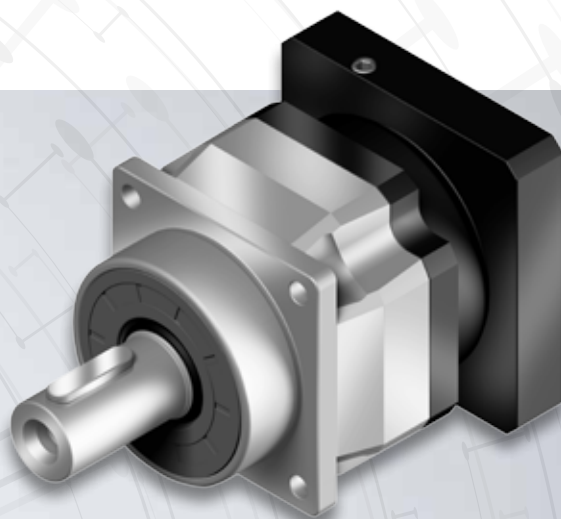


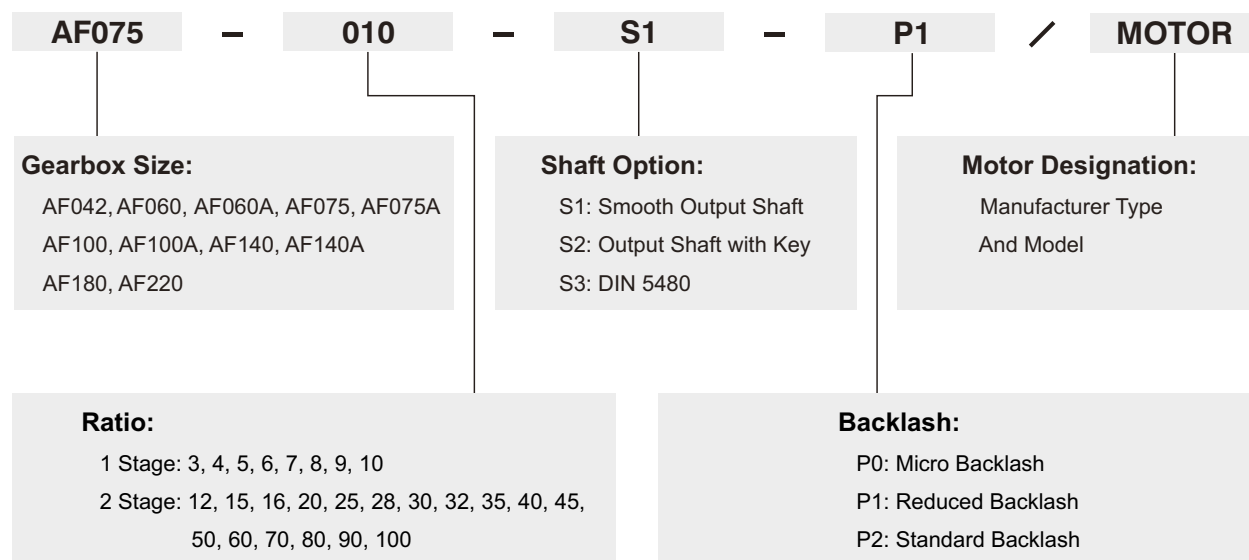
HIGH PRECISION

PLANETARY GEARBOX



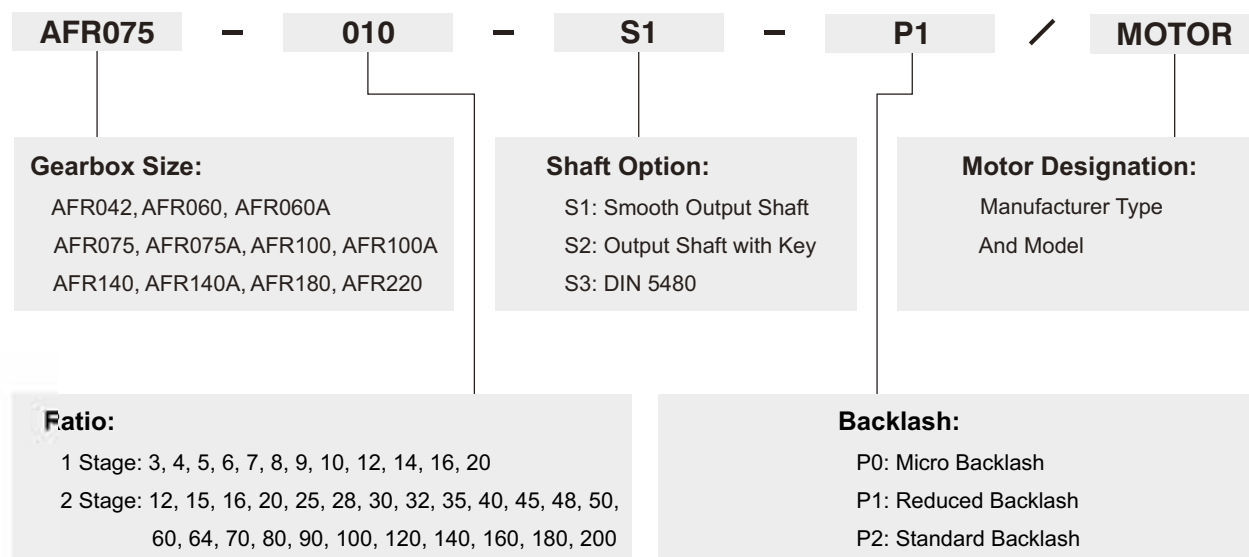
AF - AFR Series

► AF Series



Ordering Example: AF075-010-S1-P1 / SIEMENS 1FT6 041-4AF71

► AFR Series



Ordering Example: AFR075-010-S1-P1 / SIEMENS 1FT6 041-4AF71



► Performance - AF Gearbox

Model No.	Stage	Ratio ^A	AF042	AF060	AF060A	AF075	AF075A	AF100	AF100A	AF140	AF140A	AF180	AF220
Nominal Output Torque T_{2N}	1	3	20	55	–	130	–	208	–	342	–	588	1,140
		4	19	50	–	140	–	290	–	542	–	1,050	1,700
		5	22	60	–	160	–	330	–	650	–	1,200	2,000
		6	20	55	–	150	–	310	–	600	–	1,100	1,900
		7	19	50	–	140	–	300	–	550	–	1,100	1,800
		8	17	45	–	120	–	260	–	500	–	1,000	1,600
		9	14	40	–	100	–	230	–	450	–	900	1,500
		10	14	40	–	100	–	230	–	450	–	900	1,500
		12	19	50	50	140	140	290	290	542	542	1,050	1,700
		15	20	55	55	130	130	208	208	342	342	588	1,140
	2	16	19	50	50	140	140	290	290	542	542	1,050	1,700
		20	19	50	50	140	140	290	290	542	542	1,050	1,700
		25	22	60	60	160	160	330	330	650	650	1,200	2,000
		28	19	50	50	140	140	300	300	550	550	1,100	1,800
		30	20	55	55	150	150	310	310	600	600	1,100	1,900
		32	17	45	45	120	120	260	260	500	500	1,000	1,600
		35	19	50	50	140	140	300	300	550	550	1,100	1,800
		40	17	45	45	120	120	260	260	500	500	1,000	1,600
		45	14	40	40	100	100	230	230	450	450	900	1,500
		50	22	60	60	160	160	330	330	650	650	1,200	2,000
		60	20	55	55	150	150	310	310	600	600	1,100	1,900
		70	19	50	50	140	140	300	300	550	550	1,100	1,800
		80	17	45	45	120	120	260	260	500	500	1,000	1,600
		90	14	40	40	100	100	230	230	450	450	900	1,500
		100	14	40	40	100	100	230	230	450	450	900	1,500
Emergency Stop Torque T_{2NOT}^B	Nm	1,2	3~100	3 times of Nominal Output Torque									
Nominal Input Speed n_{1N}	rpm	1,2	3~100	5,000	5,000	5,000	4,000	4,000	4,000	4,000	3,000	3,000	2,000
Max. Input Speed n_{1B}	rpm	1,2	3~100	10,000	10,000	10,000	8,000	8,000	8,000	8,000	6,000	6,000	4,000
Micro Backlash P0	arcmin	1	3~10	–	–	–	≤1	–	≤1	–	≤1	–	≤1
		2	12~100	–	–	–	–	–	≤3	≤3	≤3	≤3	≤3
Reduced Backlash P1	arcmin	1	3~10	≤3	≤3	–	≤3	–	≤3	–	≤3	–	≤3
		2	12~100	≤5	≤5	≤5	≤5	≤5	≤5	≤5	≤5	≤5	≤5
Standard Backlash P2	arcmin	1	3~10	≤5	≤5	–	≤5	–	≤5	–	≤5	–	≤5
		2	12~100	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7
Torsional Rigidity	Nm/arcmin	1,2	3~100	3	7	7	14	14	25	25	50	50	145
Max. Radial Load F_{2B}^C	N	1,2	3~100	610	1,400	1,400	4,100	4,100	9,200	9,200	14,000	14,000	33,000
Max. Axial Load F_{2aB}^C	N	1,2	3~100	320	1,100	1,100	3,700	3,700	5,820	5,820	11,400	11,400	19,500
Max. Tilting Moment M_{2K}	Nm	1,2	3~100	20	85	85	380	380	970	970	1,840	1,840	2,740
Efficiency η	%	1	3~10	≥97%									
		2	12~100	≥94%									
Weight	kg	1	3~10	0.6	1.3	–	3.7	–	6.9	–	12.6	–	25.5
		2	12~100	0.8	1.5	2	4.1	5.5	8.1	10.6	16.6	20.2	31.5
Operating Temp	°C	1,2	3~100	-10°C~90°C									
Lubrication		1,2	3~100	Synthetic lubrication oils									
Degree of Gearbox Protection		1,2	3~100	IP65									
Mounting Position		1,2	3~100	all directions									
Noise ^D	dB(A)	1,2	3~100	≤56	≤58	≤60	≤60	≤63	≤63	≤65	≤65	≤67	≤70

A. Ratio ($i=N_{in}/N_{out}$)B. Max. acceleration torque $T_{2B} = 60\%$ of T_{2NOT}

C. Applied to the output shaft center at 100 rpm

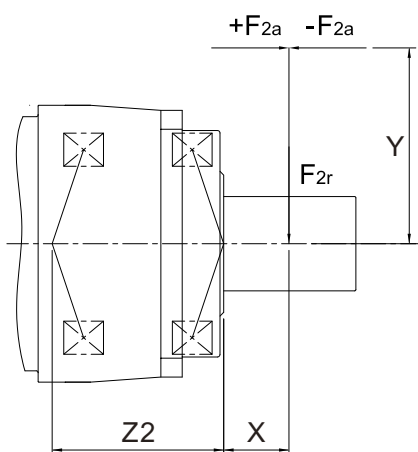
D. The dB values are measured by gearbox with ratio 10 (1-stage) or ratio 100 (2-stage), no loading at 3,000 RPM or at the respective Nominal Input Speed by bigger model size.

By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher.

► Inertia - AF Gearbox

Model No.	Stage	Ratio	AF042	AF060	AF060A	AF075	AF075A	AF100	AF100A	AF140	AF140A	AF180	AF220
Mass Moments of Inertia J _i	1	3	0.03	0.16	–	0.61	–	3.25	–	9.21	–	28.98	69.61
		4	0.03	0.14	–	0.48	–	2.74	–	7.54	–	23.67	54.37
		5	0.03	0.13	–	0.47	–	2.71	–	7.42	–	23.29	53.27
		6	0.03	0.13	–	0.45	–	2.65	–	7.25	–	22.75	51.72
		7	0.03	0.13	–	0.45	–	2.62	–	7.14	–	22.48	50.97
		8	0.03	0.13	–	0.44	–	2.58	–	7.07	–	22.59	50.84
		9	0.03	0.13	–	0.44	–	2.57	–	7.04	–	22.53	50.63
		10	0.03	0.13	–	0.44	–	2.57	–	7.03	–	22.51	50.56
	2	12	0.03	0.03	0.16	0.16	0.61	0.61	3.25	3.25	9.21	9.21	28.98
		15	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29
		16	0.03	0.03	0.14	0.14	0.48	0.48	2.74	2.74	7.54	7.54	23.67
		20	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29
		25	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29
		28	0.03	0.03	0.14	0.14	0.48	0.48	2.74	2.74	7.54	7.54	23.67
		30	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29
		32	0.03	0.03	0.14	0.14	0.48	0.48	2.74	2.74	7.54	7.54	23.67
		35	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29
		40	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29
		45	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29
		50	0.03	0.03	0.13	0.13	0.44	0.44	2.57	2.57	7.03	7.03	22.51
		60	0.03	0.03	0.13	0.13	0.44	0.44	2.57	2.57	7.03	7.03	22.51
		70	0.03	0.03	0.13	0.13	0.44	0.44	2.57	2.57	7.03	7.03	22.51
		80	0.03	0.03	0.13	0.13	0.44	0.44	2.57	2.57	7.03	7.03	22.51
		90	0.03	0.03	0.13	0.13	0.44	0.44	2.57	2.57	7.03	7.03	22.51
		100	0.03	0.03	0.13	0.13	0.44	0.44	2.57	2.57	7.03	7.03	22.51

► Max. Tilting Moment M_{2K}



$$M_{2K} = \frac{F_{2a} * Y + F_{2r} * (X+Z2)}{1000}$$

M_{2K} : [Nm]

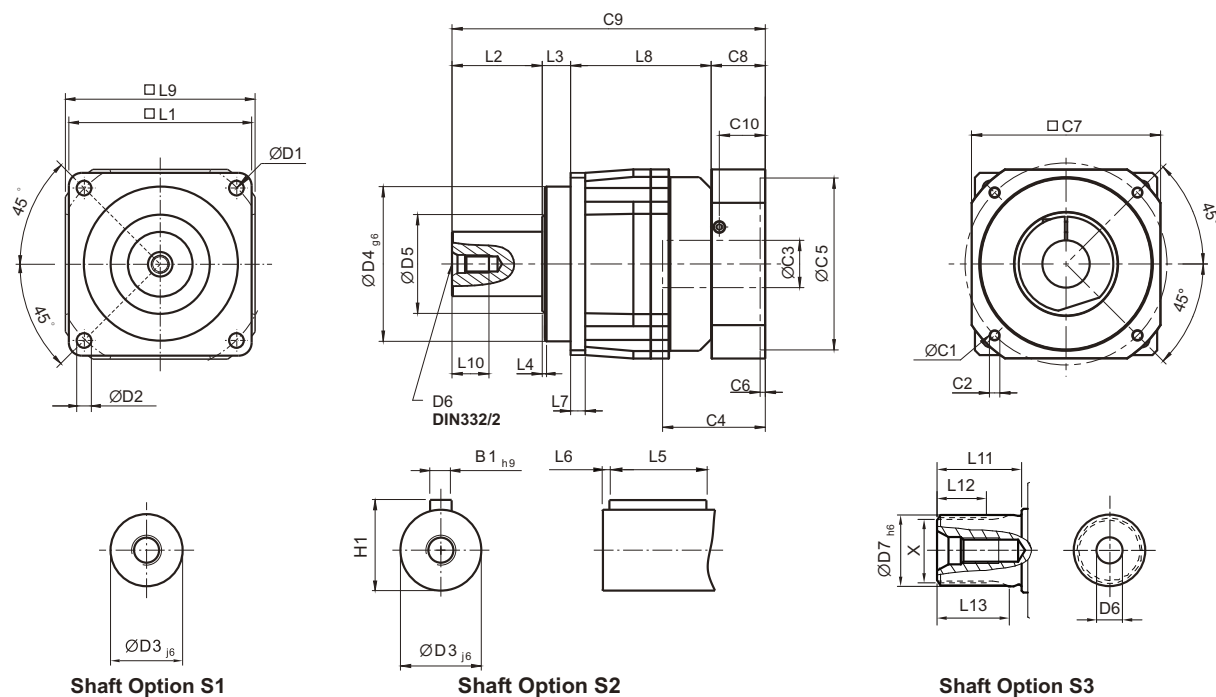
F_{2a}, F_{2r} : [N]

X, Y, Z2 : [mm]

AF / AFR	042	060	075	100	140	180	220
Z2 [mm]	31	66.5	88.7	96	114.2	138.7	127.1

Note : Applied to the output shaft center at 100 rpm.

► Dimensions (1-stage, Ratio $i=3\sim 10$) / AF Series



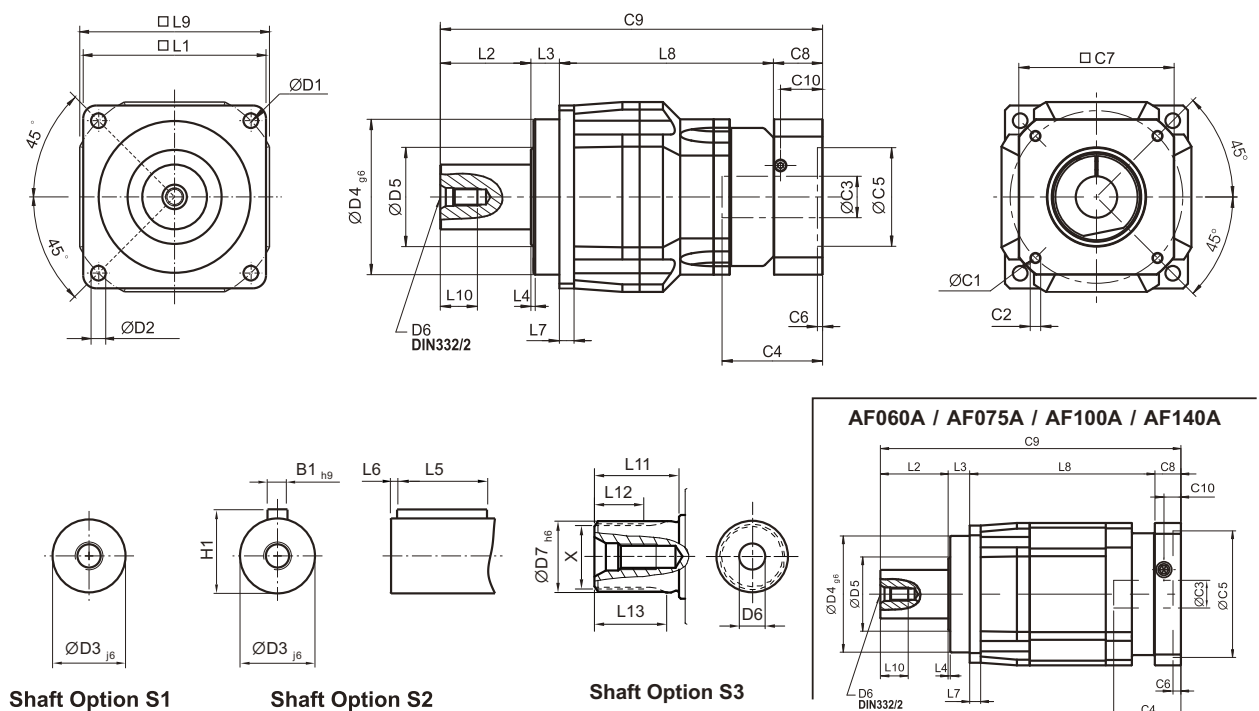
[unit: mm]

Dimension	AF042	AF060	AF075	AF100	AF140	AF180	AF220
D1	50	68	85	120	165	215	250
D2	3.4	5.5	6.8	9	11	13	17
D3 _{j6}	13	16	22	32	40	55	75
D4 _{g6}	35	60	70	90	130	160	180
D5	22	45	60	80	75	95	115
D6	M4 x 0.7P	M5 x 0.8P	M8 x 1.25P	M12 x 1.75P	M16 x 2P	M20 x 2.5P	M20 x 2.5P
D7 _{h6}	-	16	22	32	40	55	75
L1	42	62	76	105	142	180	220
L2	19.5	28.5	36	58	82	82	105
L3	6.5	20	20	30	30	30	33
L4	1	1.5	2	2	3	3	3
L5	16	25	32	40	63	70	90
L6	2	2	3	5	5	6	7
L7	4	6	7	10	12	15	20
L8	31	54.5	86.5	89.5	110	150	163.5
L9	42	60	90	115	142	180	220
L10	10	12.5	19	28	36	42	42
L11	-	26	26	26	40	41.5	52
L12	-	15	15	15	20	21.5	28
L13	-	21	22.5	23	33.5	33.5	45
C1 ¹	46	70	100	130	165	215	235
C2 ¹	M4 x 0.7P	M5 x 0.8P	M6 x 1P	M8 x 1.25P	M10 x 1.5P	M12 x 1.75P	M12 x 1.75P
C3 ¹	≤11 / ≤12 ²	≤14 / ≤16 ²	≤19 / ≤24	≤32	≤38	≤48	≤55
C4 ¹	25	34	40	50	60	85	116
C5 ¹	30	50	80	110	130	180	200
C6 ¹	3.5	8	4	5	6	6	6
C7 ¹	42	60	90	115	142	190	220
C8 ¹	29.5	19	17	19.5	22.5	29	63
C9 ¹	86.5	122	159.5	197	244.5	291	364.5
C10 ¹	8.75	13.5	10.75	13	15	20.75	53
B1 _{h9}	5	5	6	10	12	16	20
H1	15	18	24.5	35	43	59	79.5
X DIN5480	-	W16x0.8x 30x18x6m	W22x1.25x 30x16x6m	W32x1.25x 30x24x6m	W40x2x 30x18x6m	W55x2x 30x26x6m	W70x2x 30x34x6m

1. C1-C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.

2. AF042 ratio 5, 10 offers C3 ≤ 12 option; AF062 ratio 5, 10 offers C3 ≤ 16 option.

► Dimensions (2-stage, Ratio $i=12\sim100$) / AF Series



[unit: mm]

Dimension	AF042	AF060	AF060A	AF075	AF075A	AF100	AF100A	AF140	AF140A	AF180	AF220
D1	50	68		85		120		165		215	250
D2	3.4	5.5		6.8		9		11		13	17
D3 _{j6}	13	16		22		32		40		55	75
D4 _{g6}	35	60		70		90		130		160	180
D5	22	45		60		80		75		95	115
D6	M4x0.7P	M5 x 0.8P		M8 x 1.25P		M12 x 1.75P		M16 x 2P		M20x2.5P	M20x2.5P
D7	56	16		22		32		40		55	75
L1	42	62		76		105		142		180	220
L2	19.5	28.5		36		58		82		82	105
L3	6.5	20		20		30		30		30	33
L4	1	1.5		2		2		3		3	3
L5	16	25		32		40		63		70	90
L6	2	2		3		5		5		6	7
L7	4	6		7		10		12		15	20
L8	58.5	65.5	91.5	119.5	134.5	131	150.5	166.5	181.5	205.5	248
L9	42	60		90		115		142		180	220
L10	10	12.5		19		28		36		42	42
L11	-	26		26		26		40		41.5	52
L12	-	15		15		15		20		21.5	28
L13	-	21		22.5		23		33.5		33.5	45
C1 ³	46	46	70	70	100	100	130	130	165	165	215
C2 ³	M4x0.7P	M4x0.7P	M5 x 0.8P	M5 x 0.8P	M6 x 1P	M6 x 1P	M8x1.25P	M8x1.25P	M10x1.5P	M10x1.5P	M12x1.75P
C3 ³	≤11 / ≤12	≤11 / ≤12	≤14 / ≤16	≤14 / ≤15.875 / ≤16	≤19 / ≤24	≤19 / ≤24	≤32	≤32	≤38	≤38	≤48
C4 ³	25	25	34	34	40	40	50	50	60	60	85
C5 ³	30	30	50	50	80	80	110	110	130	130	180
C6 ³	3.5	3.5	8	8	4	4	5	5	6	6	6
C7 ³	42	42	60	60	90	90	115	115	142	142	190
C8 ³	29.5	29.5	19	19	17	17	19.5	19.5	22.5	22.5	29
C9 ³	114	143.5	159	194.5	207.5	207.5	258	298	316	340	415
C10 ³	8.75	8.75	13.5	13.5	10.75	10.75	13	13	15	15	20.75
B1 _{h9}	5	5		6		10		12		16	20
H1	15	18		24.5		35		43		59	79.5
X DIN5480	-	W16x0.8x 30x18x6m		W22x1.25x 30x16x6m		W32x1.25x 30x24x6m		W40x2x 30x18x6m		W55x2x 30x26x6m	W70x2x 30x34x6m

3. C1~C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.

► Performance - AFR Gearbox

Model No.		Stage	Ratio ^A	AFR042	AFR060	AFR060A	AFR075	AFR075A	AFR100	AFR100A	AFR140	AFR140A	AFR180	AFR220	
Nominal Output Torque T _{2N}	Nm	1	3	9	36	—	90	—	195	—	342	—	588	1,140	
			4	12	48	—	120	—	260	—	520	—	1,040	1,680	
			5	15	60	—	150	—	325	—	650	—	1,200	2,000	
			6	18	55	—	150	—	310	—	600	—	1,100	1,900	
			7	19	50	—	140	—	300	—	550	—	1,100	1,800	
			8	17	45	—	120	—	260	—	500	—	1,000	1,600	
			9	14	40	—	100	—	230	—	450	—	900	1,500	
			10	14	60	—	150	—	325	—	650	—	1,200	2,000	
			12	—	55	—	150	—	310	—	600	—	1,100	1,900	
			14	—	42	—	140	—	300	—	550	—	1,100	1,800	
		16	—	45	—	120	—	260	—	500	—	1,000	1,600		
		20	—	40	—	100	—	230	—	450	—	900	1,500		
		2	12	12	—	—	—	—	—	—	—	—	—	—	—
			15	14	—	—	—	—	—	—	—	—	—	—	—
			16	15	—	—	—	—	—	—	—	—	—	—	—
			20	14	—	—	—	—	—	—	—	—	—	—	—
			25	15	60	60	150	150	325	325	650	650	1,200	2,000	
			28	19	50	50	140	140	300	300	550	550	1,100	1,800	
			30	20	55	55	150	150	310	310	600	600	1,100	1,900	
			32	17	45	45	120	120	260	260	500	500	1,000	1,600	
	35		19	50	50	140	140	300	300	550	550	1,100	1,800		
	40		17	45	45	120	120	260	260	500	500	1,000	1,600		
	45	14	40	40	100	100	230	230	450	450	900	1,500			
	48	—	—	55	150	150	310	310	600	600	1,100	1,900			
	50	14	60	60	150	150	325	325	650	650	1,200	2,000			
	60	20	55	55	150	150	310	310	600	600	1,100	1,900			
	64	—	—	45	120	120	260	260	500	500	1,000	1,600			
	70	19	50	50	140	140	300	300	550	550	1,100	1,800			
	80	17	45	45	120	120	260	260	500	500	1,000	1,600			
	90	14	40	40	100	100	230	230	450	450	900	1,500			
	100	14	40	60	150	150	325	325	650	650	1,200	2,000			
	120	—	—	55	150	150	310	310	600	600	1,100	1,900			
	140	—	—	50	140	140	300	300	550	550	1,100	1,800			
	160	—	—	45	120	120	260	260	550	550	1,000	1,600			
	180	—	—	40	100	100	230	230	450	450	900	1,500			
	200	—	—	40	100	100	230	230	450	450	900	1,500			
Emergency Stop Torque T _{2NOT} ^B	Nm	1,2	3~200 3 times of Nominal Output Torque												
Nominal Input Speed n _{1N}	rpm	1,2	3~200	5,000	5,000	5,000	4,000	4,000	4,000	4,000	3,000	3,000	3,000	2,000	
Max. Input Speed n _{1B}	rpm	1,2	3~200	10,000	10,000	10,000	8,000	8,000	8,000	8,000	6,000	6,000	6,000	4,000	
Micro Backlash P0	arcmin	1	3~20	—	—	—	≤2	—	≤2	—	≤2	—	≤2	≤2	
		2	12~200	—	—	—	≤4	≤4	≤4	≤4	≤4	≤4	≤4	≤4	
Reduced Backlash P1	arcmin	1	3~20	≤4	≤4	—	≤4	—	≤4	—	≤4	—	≤4	≤4	
		2	12~200	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	
Standard Backlash P2	arcmin	1	3~20	≤6	≤6	—	≤6	—	≤6	—	≤6	—	≤6	≤6	
		2	12~200	≤9	≤9	≤9	≤9	≤9	≤9	≤9	≤9	≤9	≤9	≤9	
Torsional Rigidity	Nm/arcmin	1,2	3~200	3	7	7	14	14	25	25	50	50	145	225	
Max. Radial Load F _{2B} ^C	N	1,2	3~200	610	1,400	1,400	4,100	4,100	9,200	9,200	14,000	14,000	18,000	33,000	
Max. Axial Load F _{2AB} ^C	N	1,2	3~200	320	1,100	1,100	3,700	3,700	5,800	5,800	11,400	11,400	19,500	16,300	
Max. Tilting Moment M _{2K}	Nm		3~200	20	85	85	380	380	970	970	1,840	1,840	2,740	5,030	
Efficiency η	%	1	3~20	≥95%											
		2	12~200	≥92%											
Weight	kg	1	3~20	0.9	2.1	—	6.4	—	11.3	—	22.5	—	44	77	
		2	12~200	1.2	1.9	2.8	4.8	8	10.6	15.1	21	29.2	41	75	
Operating Temp	°C	1,2	3~200	-10°C~+90°C											
Lubrication		1,2	3~200	Synthetic lubrication oils											
Degree of Gearbox Protection		1,2	3~200	IP65											
Mounting Position		1,2	3~200	all directions											
Noise ^D	dB(A)	1,2	3~200	≤61	≤63	≤65	≤65	≤68	≤68	≤70	≤70	≤72	≤72	≤74	

A. Ratio ($i=N_n/N_{out}$)B. Max. acceleration torque $T_{2B} = 60\%$ of T_{2NOT}

C. Applied to the output shaft center at 100 rpm

D. The dB values are measured by gearbox with ratio 10 (1-stage) or ratio 100 (2-stage), no loading at 3,000 RPM or at the respective Nominal Input Speed by bigger model size.

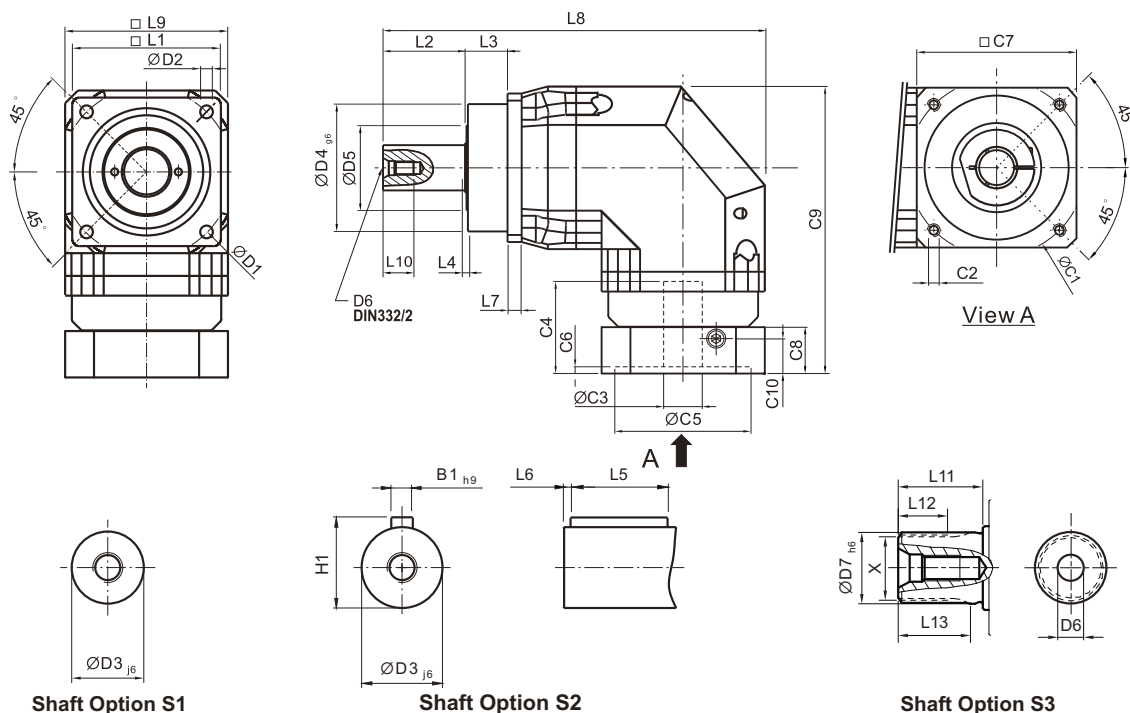
By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher.

► Inertia - AFR Gearbox

Model No.		Stage	Ratio	AFR042	AFR060	AFR060A	AFR075	AFR075A	AFR100	AFR100A	AFR140	AFR140A	AFR180	AFR220
Mass Moments of Inertia J_i	kg · cm ²	1	3~10	0.09	0.35	—	2.25	—	6.84	—	23.4	—	68.9	135.4
			12~20	—	0.07	—	1.87	—	6.25	—	21.8	—	65.6	119.8
		2	12~20	0.09	—	—	—	—	—	—	—	—	—	—
			25~90	0.09	0.09	0.35	0.35	2.25	2.25	6.84	6.84	23.4	23.4	68.9
			48, 64	—	—	0.07	0.31	1.87	1.87	6.25	6.25	21.8	21.8	65.6
			100~200	—	—	0.07	0.31	1.87	1.87	6.25	6.25	21.8	21.8	65.6



► Dimensions (1-stage, Ratio $i=3\sim 20$) / AFR Series

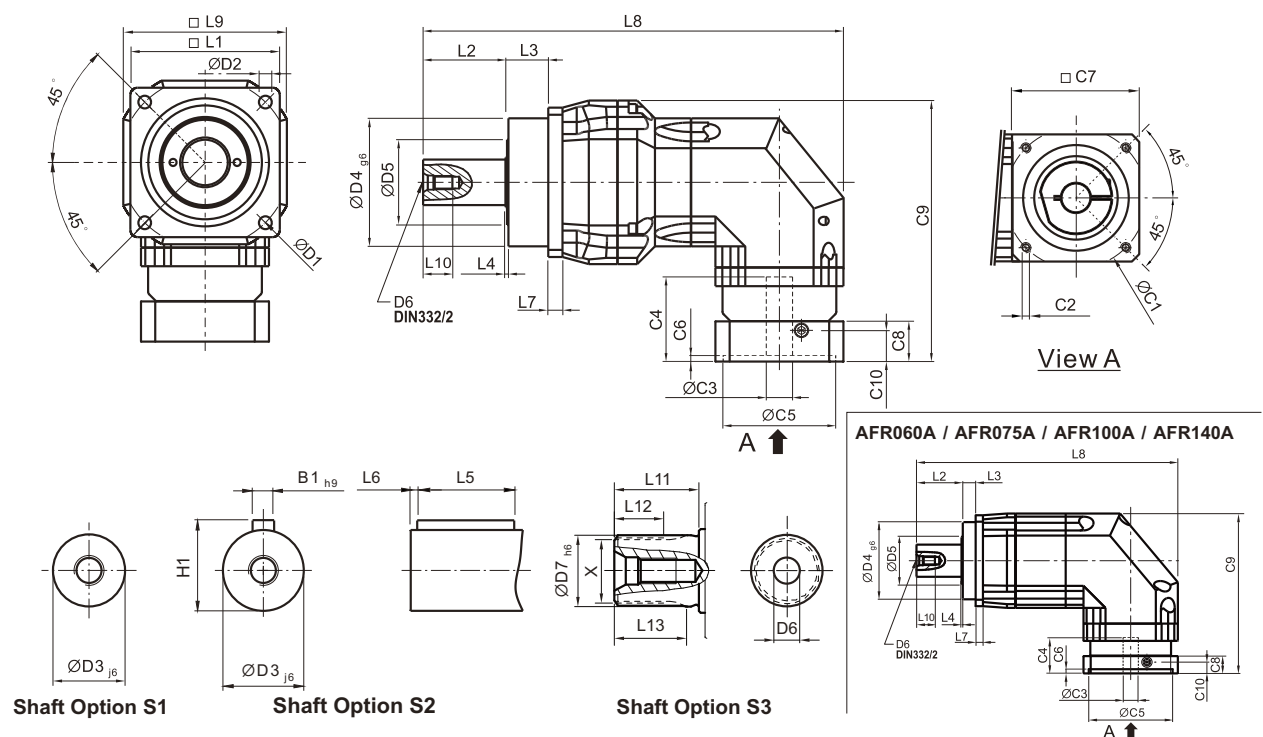


[unit: mm]

Dimension	AFR042	AFR060	AFR075	AFR100	AFR140	AFR180	AFR220
D1	50	68	85	120	165	215	250
D2	3.4	5.5	6.8	9	11	13	17
D3 _{j6}	13	16	22	32	40	55	75
D4 _{g6}	35	60	70	90	130	160	180
D5	22	45	60	80	75	95	115
D6	M4 x 0.7P	M5 x 0.8P	M8 x 1.25P	M12 x 1.75P	M16 x 2P	M20 x 2.5P	M20 x 2.5P
D7 _{h6}	-	16	22	32	40	55	75
L1	42	62	76	105	142	180	220
L2	19.5	28.5	36	58	82	82	105
L3	6.5	20	20	30	30	30	33
L4	1	1.5	2	2	3	3	3
L5	16	25	32	40	63	70	90
L6	2	2	3	5	5	6	7
L7	4	6	7	10	12	15	20
L8	111.5	150	219	269.5	338.5	397	484
L9	42	60	90	115	142	180	220
L10	10	12.5	19	28	36	42	42
L11	-	26	26	26	40	41.5	52
L12	-	15	15	15	20	21.5	28
L13	-	21	22.5	23	33.5	33.5	45
C1 ¹	46	70	100	130	165	215	235
C2 ¹	M4 x 0.7P	M5 x 0.8P	M6 x 1P	M8 x 1.25P	M10 x 1.5P	M12 x 1.75P	M12 x 1.75P
C3 ¹	≤11 / ≤12	≤14 / ≤16	≤19 / ≤24	≤32	≤38	≤48	≤55
C4 ¹	25	34	40	50	60	85	116
C5 ¹	30	50	80	110	130	180	200
C6 ¹	3.5	8	4	5	6	6	6
C7 ¹	42	60	90	115	142	190	220
C8 ¹	29.5	19	17	19.5	22.5	29	63
C9 ¹	90.5	111.5	152.5	191.5	235.5	303.5	378.5
C10 ¹	8.75	13.5	10.75	13	15	20.75	53
B1 _{h9}	5	5	6	10	12	16	20
H1	15	18	24.5	35	43	59	79.5
X DIN5480	-	W16x0.8x 30x18x6m	W22x1.25x 30x16x6m	W32x1.25x 30x24x6m	W40x2x 30x18x6m	W55x2x 30x26x6m	W70x2x 30x34x6m

1. C1~C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.

► Dimensions (2-stage, Ratio $i=12\sim200$) / AFR Series

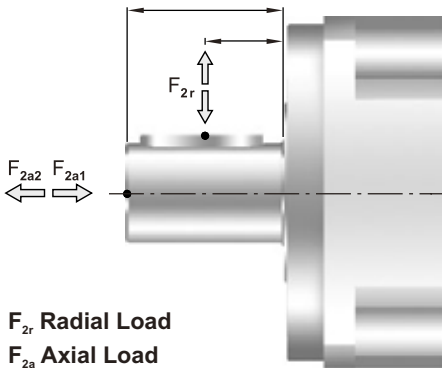


[unit: mm]

Dimension	AFR042	AFR060	AFR060A	AFR075	AFR075A	AFR100	AFR100A	AFR140	AFR140A	AFR180	AFR220
D1	50	68		85		120		165		215	250
D2	3.4	5.5		6.8		9		11		13	17
D3 _{j6}	13	16		22		32		40		55	75
D4 _{g6}	35	60		70		90		130		160	180
D5	22	45		60		80		75		95	115
D6	M4x0.7P	M5 x 0.8P		M8 x 1.25P		M12 x 1.75P		M16 x 2P		M20x2.5P	M20x2.5P
D7	-	16		22		32		40		55	75
L1	42	62		76		105		142		180	220
L2	19.5	28.5		36		58		82		82	105
L3	6.5	20		20		30		30		30	33
L4	1	1.5		2		2		3		3	3
L5	16	25		32		40		63		70	90
L6	2	2		3		5		5		6	7
L7	4	6		7		10		12		15	20
L8	139	168.5	187	222.5	267	295.5	330.5	370.5	410	434	521
L9	42	60		90		115		142		180	220
L10	10	12.5		19		28		36		42	42
L11	-	26		26		26		40		41.5	52
L12	-	15		15		15		20		21.5	28
L13	-	21		22.5		23		33.5		33.5	45
C1 ²	46	46	70	70	100	100	130	130	165	165	215
C2 ²	M4x0.7P	M4x0.7P	M5 x 0.8P	M5 x 0.8P	M6 x 1P	M6 x 1P	M8x1.25P	M8x1.25P	M10x1.5P	M10x1.5P	M12x1.75P
C3 ²	≤11/≤12	≤11/≤12	≤14/≤16	≤14/≤15.875/≤16	≤19/≤24	≤19/≤24	≤32	≤32	≤38	≤38	≤48
C4 ²	25	25	34	34	40	40	50	50	60	60	85
C5 ²	30	30	50	50	80	80	110	110	130	130	180
C6 ²	3.5	3.5	8	8	4	4	5	5	6	6	6
C7 ²	42	42	60	60	90	90	115	115	142	142	190
C8 ²	29.5	29.5	19	19	17	17	19.5	19.5	22.5	22.5	29
C9 ²	90.5	99.5	111.5	126.5	152.5	165	191.5	205	235.5	254.5	323.5
C10 ²	8.75	8.75	13.5	13.5	10.75	10.75	13	13	15	15	20.75
B1 _{h9}	5	5		6		10		12		16	20
H1	15	18		24.5		35		43		59	79.5
X DIN5480	-	W16x0.8x 30x18x6m		W22x1.25x 30x16x6m		W32x1.25x 30x24x6m		W40x2x 30x18x6m		W55x2x 30x26x6m	W70x2x 30x34x6m

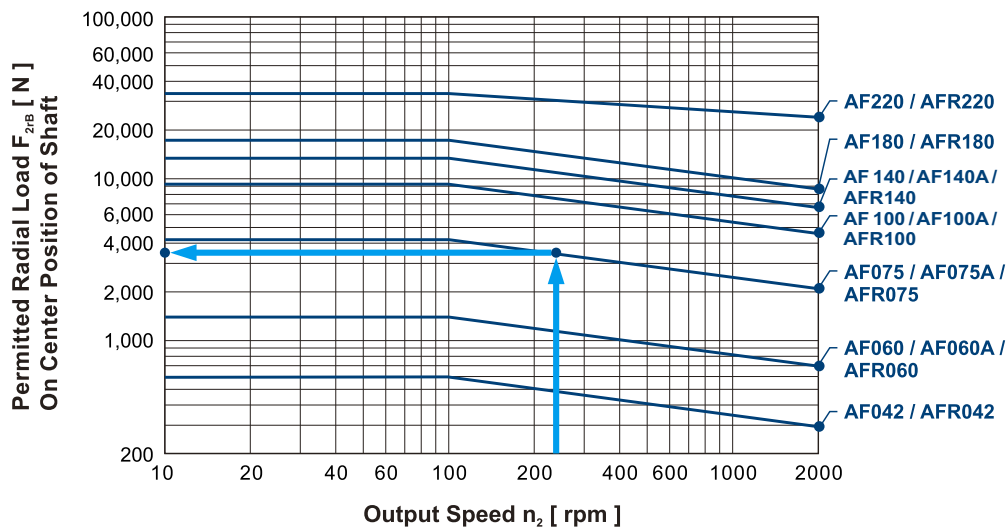
2. C1~C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.

► Permitted Radial and Axial Loads



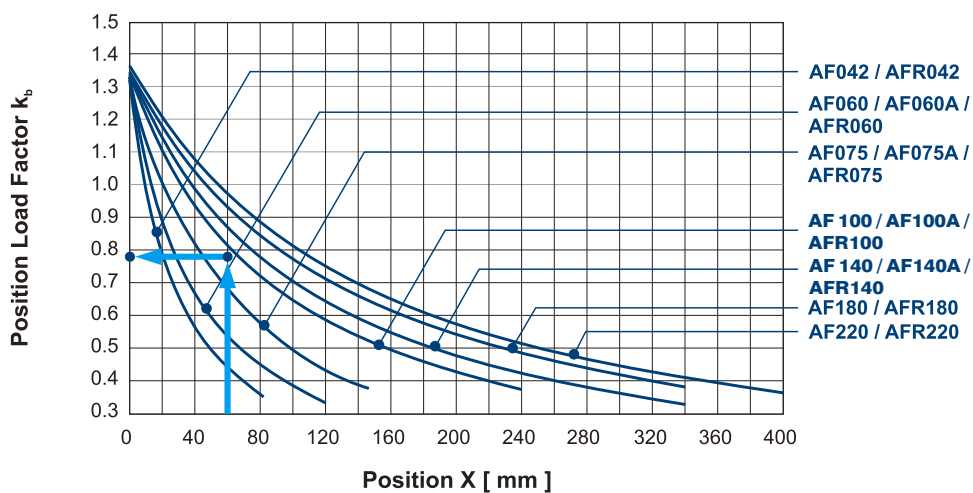
The permitted radial and axial loads on output shaft of the gearbox depend on the design of the gearbox supporting bearings.

APEX use the extension straddle oversized ball bearing design. It can take heavy load from both axes.



If radial force F_{2r} is exerted on the center of the output shaft $X=1/2 \times L$.

The permitted radial load is given on left diagram.



If radial force F_{2r} is not exerted on the center of the output shaft $X < 1/2 \times L$ or $X > 1/2 \times L$.

The permitted radial and axial loads can be calculated by the position load factor k_b on the left diagram.

