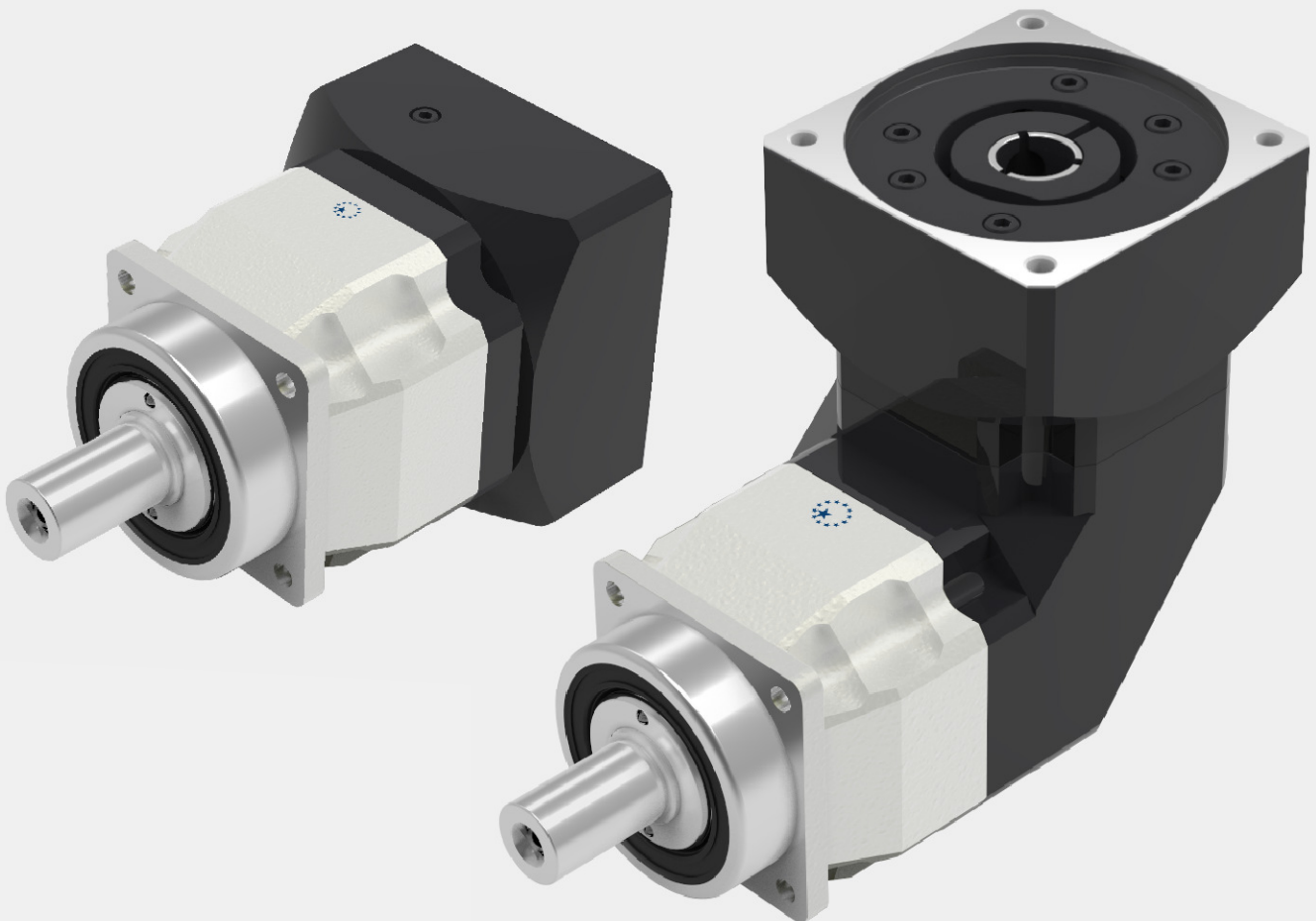




APEX DYNAMICS, INC.

**HIGH PRECISION
HIGH SPEED
PLANETARY GEARBOX**

AF / AFR Series



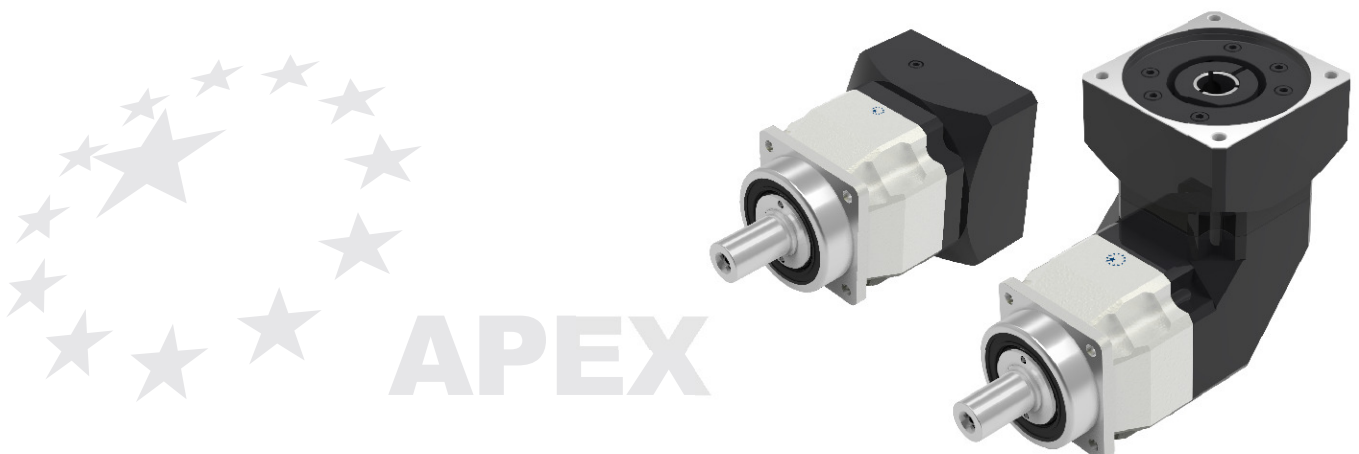
Stainless



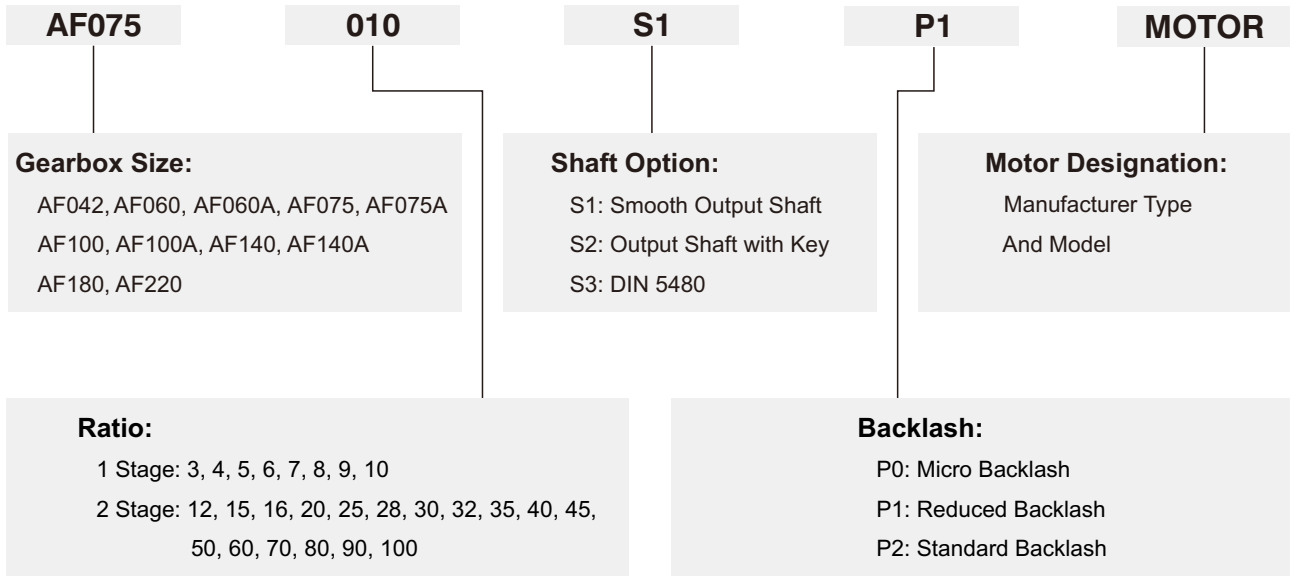
Apex Dynamics, Inc. is the world's most productive manufacturer of servomotor drive planetary gearboxes for precision automation machinery. From our 800,000+ square foot ISO 9001:2008 manufacturing facility, based in Taichung, Taiwan, we manufacture to stock using the newest precision machine tools and quality test and inspection equipment. Complete focus on quality and precision allows us to produce our high quality gearheads at precision levels down to less than 1 arc minute (1/60 th of a degree), with consistency and high reliability.

Based on more than twenty years of accumulated manufacturing and marketing experience, plus the highest level of technical production capabilities, Apex Dynamics, Inc. designs and builds technically advanced, high speed, low backlash servo application planetary gearboxes. Our Break through patented technology (over 6 patents), provides the customer with the optimum high precision helical reducer at a reasonable price. We are continuously improving processes, finding proper and effective methods to provide customers new solutions for difficult applications, and developing new products.

The primary focus in daily operation is quality. We pride ourselves on our dedication to quality; our duty - is customer satisfaction.

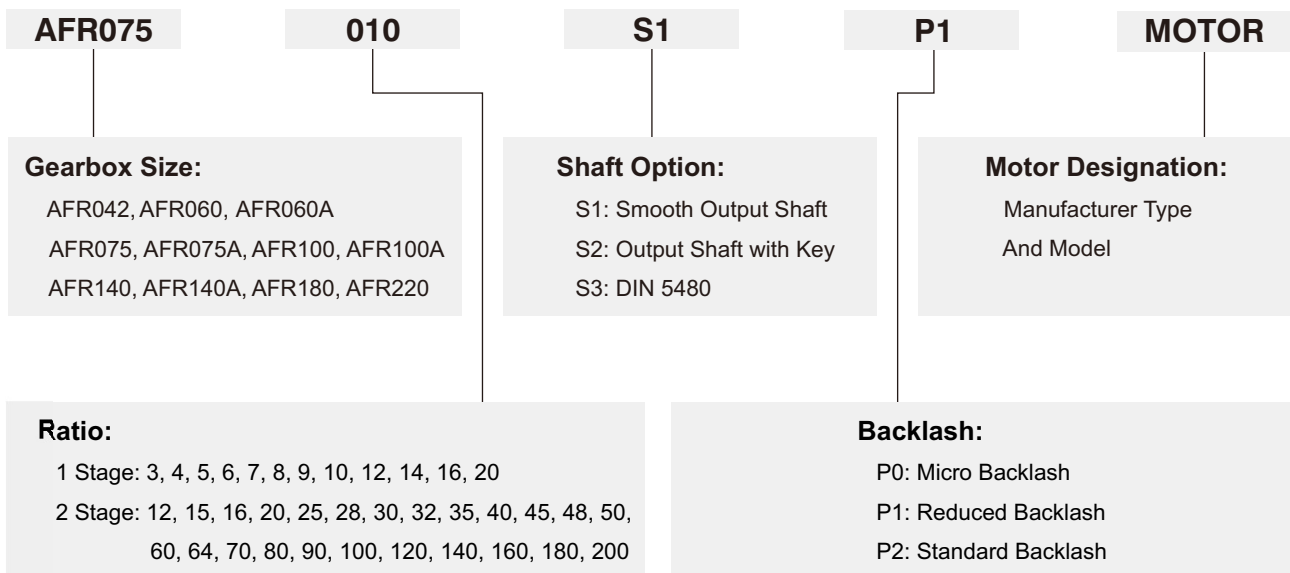


AF Series



Ordering Example: AF075-010-S1-P1 / SIEMENS 1FT6 041-4AF71

AFR Series



Ordering Example: AFR075-010-S1-P1 / SIEMENS 1FT6 041-4AF71

Specifications / AF Series

Gearbox Performance

Model No.		Stage	Ratio ^A	AF042	AF060	AF060A	AF075	AF075A	AF100	AF100A	AF140	AF140A	AF180	AF220
Nominal Output Torque T_{2N}	Nm	1	3	20	55	-	130	-	208	-	342	-	588	1,140
			4	19	50	-	140	-	290	-	542	-	1,050	1,700
			5	22	60	-	160	-	330	-	650	-	1,200	2,000
			6	20	55	-	150	-	310	-	600	-	1,100	1,900
			7	19	50	-	140	-	300	-	550	-	1,100	1,800
			8	17	45	-	120	-	260	-	500	-	1,000	1,600
			9	14	40	-	100	-	230	-	450	-	900	1,500
			10	14	40	-	100	-	230	-	450	-	900	1,500
			12	19	50	50	140	140	290	290	542	542	1,050	1,700
			15	20	55	55	130	130	208	208	342	342	588	1,140
		16	19	50	50	140	140	290	290	542	542	1,050	1,700	
		20	19	50	50	140	140	290	290	542	542	1,050	1,700	
		25	22	60	60	160	160	330	330	650	650	1,200	2,000	
		28	19	50	50	140	140	300	300	550	550	1,100	1,800	
		30	20	55	55	150	150	310	310	600	600	1,100	1,900	
		32	17	45	45	120	120	260	260	500	500	1,000	1,600	
		35	19	50	50	140	140	300	300	550	550	1,100	1,800	
		40	17	45	45	120	120	260	260	500	500	1,000	1,600	
		45	14	40	40	100	100	230	230	450	450	900	1,500	
		50	22	60	60	160	160	330	330	650	650	1,200	2,000	
60	20	55	55	150	150	310	310	600	600	1,100	1,900			
70	19	50	50	140	140	300	300	550	550	1,100	1,800			
80	17	45	45	120	120	260	260	500	500	1,000	1,600			
90	14	40	40	100	100	230	230	450	450	900	1,500			
100	14	40	40	100	100	230	230	450	450	900	1,500			
Emergency Stop Torque T_{2NOT} ^B	Nm	1,2	3~100	3 times of Nominal Output Torque										
Nominal Input Speed n_{1N}	rpm	1,2	3~100	5,000	5,000	5,000	4,000	4,000	4,000	4,000	3,000	3,000	3,000	2,000
Max. Input Speed n_{1B}	rpm	1,2	3~100	10,000	10,000	10,000	8,000	8,000	8,000	8,000	6,000	6,000	6,000	4,000
Micro Backlash P0	arcmin	1	3~10	-	-	-	≤1	-	≤1	-	≤1	-	≤1	≤1
		2	12~100	-	-	-	-	-	≤3	≤3	≤3	≤3	≤3	≤3
Reduced Backlash P1	arcmin	1	3~10	≤3	≤3	-	≤3	-	≤3	-	≤3	-	≤3	≤3
		2	12~100	≤5	≤5	≤5	≤5	≤5	≤5	≤5	≤5	≤5	≤5	≤5
Standard Backlash P2	arcmin	1	3~10	≤5	≤5	-	≤5	-	≤5	-	≤5	-	≤5	≤5
		2	12~100	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7
Torsional Rigidity	Nm/arcmin	1,2	3~100	3	7	7	14	14	25	25	50	50	145	225
Max. Radial Load F_{2rB} ^C	N	1,2	3~100	610	1,400	1,400	4,100	4,100	9,200	9,200	14,000	14,000	18,000	33,000
Max. Axial Load F_{2aB} ^C	N	1,2	3~100	320	1,100	1,100	3,700	3,700	5,820	5,820	11,400	11,400	19,500	16,300
Service Life ^D	hr	1,2	3~100	30,000										
Efficiency η	%	1	3~10	≥97%										
		2	12~100	≥94%										
Weight	kg	1	3~10	0.6	1.3	-	3.7	-	6.9	-	13.7	-	28	48
		2	12~100	0.8	1.5	2	4.1	5.5	8.1	10.6	16.6	20.2	33	60
Operating Temp	°C	1,2	3~100	-10°C~90°C										
Lubrication		1,2	3~100	Synthetic lubrication oils										
Degree of Gearbox Protection		1,2	3~100	IP65										
Mounting Position		1,2	3~100	all directions										
Noise ($n_1=3000$ rpm, $i=10$, No load) ^E	dB(A)	1,2	3~100	≤56	≤58	≤60	≤60	≤63	≤63	≤65	≤65	≤67	≤67	≤70

A. Ratio ($i=N_n/N_{out}$)B. Max. acceleration torque T_{2B} = 60% of T_{2NOT}

C. Applied to the output shaft center at 100 rpm

D. For continuous operation, the service life time is less than 15,000 hrs

E. These values are measured by gearbox with ratio = 10 (1-stage) or ratio = 100 (2-stage) at 3,000 rpm no loading.

By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher

A. Ratio ($i=N_n/N_{out}$)B. Max. acceleration torque T_{2B} = 60% of T_{2NOT}

C. Applied to the output shaft center at 100 rpm

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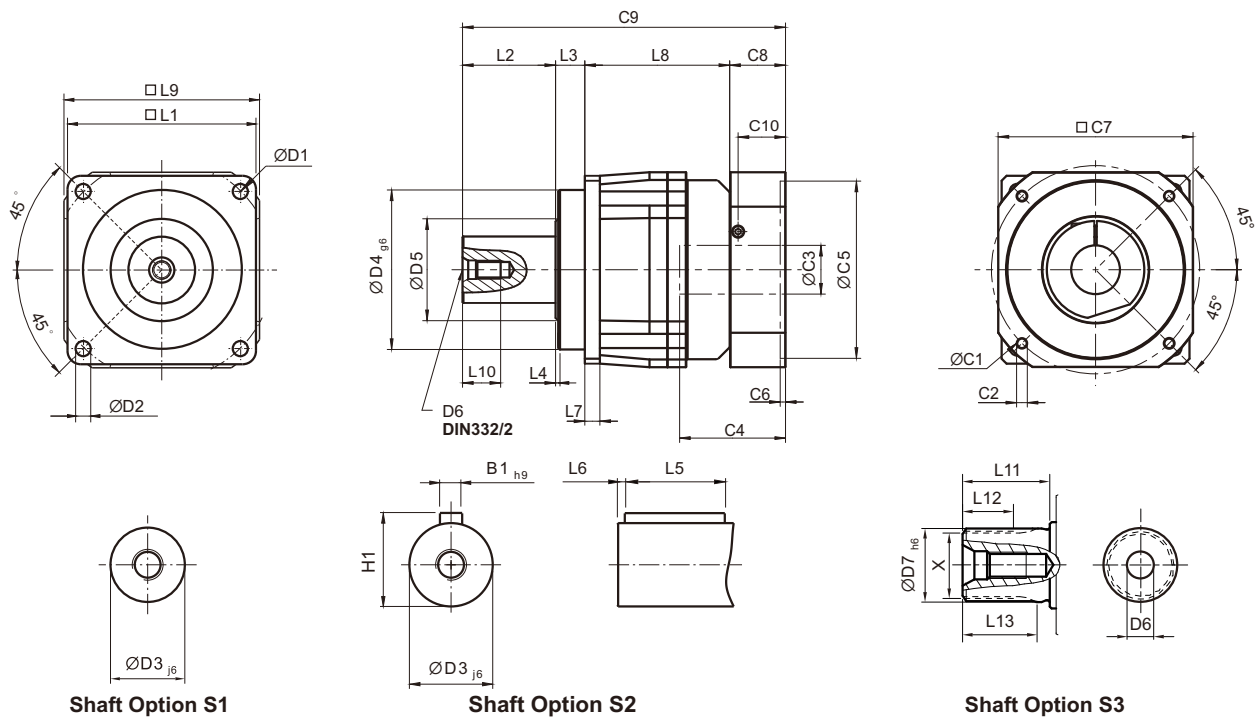
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Gearbox Inertia

Model No.	Stage	Ratio	AF042	AF060	AF060A	AF075	AF075A	AF100	AF100A	AF140	AF140A	AF180	AF220	
Mass Moments of Inertia J ₁	1	3	0.03	0.16	-	0.61	-	3.25	-	9.21	-	28.98	69.61	
		4	0.03	0.14	-	0.48	-	2.74	-	7.54	-	23.67	54.37	
		5	0.03	0.13	-	0.47	-	2.71	-	7.42	-	23.29	53.27	
		6	0.03	0.13	-	0.45	-	2.65	-	7.25	-	22.75	51.72	
		7	0.03	0.13	-	0.45	-	2.62	-	7.14	-	22.48	50.97	
		8	0.03	0.13	-	0.44	-	2.58	-	7.07	-	22.59	50.84	
		9	0.03	0.13	-	0.44	-	2.57	-	7.04	-	22.53	50.63	
		10	0.03	0.13	-	0.44	-	2.57	-	7.03	-	22.51	50.56	
		12	0.03	0.03	0.16	0.16	0.61	0.61	3.25	3.25	9.21	9.21	28.98	28.98
		15	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29	23.29
	16	0.03	0.03	0.14	0.14	0.48	0.48	2.74	2.74	7.54	7.54	23.67	23.67	
	20	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29	23.29	
	25	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29	23.29	
	28	0.03	0.03	0.14	0.14	0.48	0.48	2.74	2.74	7.54	7.54	23.67	23.67	
	30	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29	23.29	
	32	0.03	0.03	0.14	0.14	0.48	0.48	2.74	2.74	7.54	7.54	23.67	23.67	
	35	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29	23.29	
	40	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29	23.29	
	45	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29	23.29	
	50	0.03	0.03	0.13	0.13	0.44	0.44	2.57	2.57	7.03	7.03	22.51	22.51	
60	0.03	0.03	0.13	0.13	0.44	0.44	2.57	2.57	7.03	7.03	22.51	22.51		
70	0.03	0.03	0.13	0.13	0.44	0.44	2.57	2.57	7.03	7.03	22.51	22.51		
80	0.03	0.03	0.13	0.13	0.44	0.44	2.57	2.57	7.03	7.03	22.51	22.51		
90	0.03	0.03	0.13	0.13	0.44	0.44	2.57	2.57	7.03	7.03	22.51	22.51		
100	0.03	0.03	0.13	0.13	0.44	0.44	2.57	2.57	7.03	7.03	22.51	22.51		

Dimensions (1-stage, Ratio $i=3\sim 10$) / AF Series

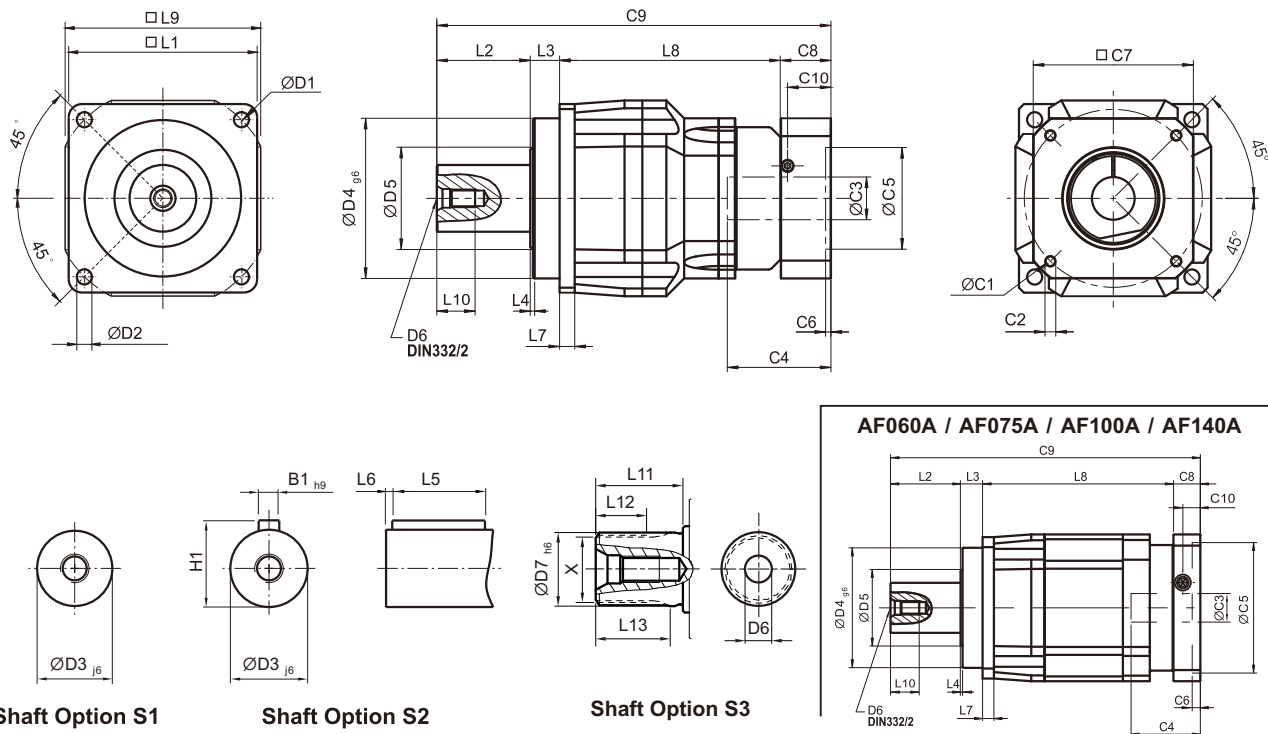


[unit: mm]

Dimension	AF042	AF060	AF075	AF100	AF140	AF180	AF220
D1	50	68	85	120	165	215	250
D2	3.4	5.5	6.8	9	11	13	17
D3 _{j6}	13	16	22	32	40	55	75
D4 _{g6}	35	60	70	90	130	160	180
D5	22	45	60	80	75	95	115
D6	M4 x 0.7P	M5 x 0.8P	M8 x 1.25P	M12 x 1.75P	M16 x 2P	M20 x 2.5P	M20 x 2.5P
D7 _{h6}	-	16	22	32	40	55	75
L1	42	62	76	105	142	180	220
L2	19.5	28.5	36	58	82	82	105
L3	6.5	20	20	30	30	30	33
L4	1	1.5	2	2	3	3	3
L5	16	25	32	40	63	70	90
L6	2	2	3	5	5	6	7
L7	4	6	7	10	12	15	20
L8	31	54.5	86.5	89.5	110	150	163.5
L9	42	60	90	115	142	180	220
L10	10	12.5	19	28	36	42	42
L11	-	26	26	26	40	41.5	52
L12	-	15	15	15	20	21.5	28
L13	-	21	22.5	23	33.5	33.5	45
C1 ¹	46	70	100	130	165	215	235
C2 ¹	M4 x 0.7P	M5 x 0.8P	M6 x 1P	M8 x 1.25P	M10 x 1.5P	M12 x 1.75P	M12 x 1.75P
C3 ¹	≤11 / ≤12 ²	≤14 / ≤16 ²	≤19 / ≤24	≤32	≤38	≤48	≤55
C4 ¹	25	34	40	50	60	85	116
C5 ¹	30	50	80	110	130	180	200
C6 ¹	3.5	8	4	5	6	6	6
C7 ¹	42	60	90	115	142	190	220
C8 ¹	29.5	19	17	19.5	22.5	29	63
C9 ¹	86.5	122	159.5	197	244.5	291	364.5
C10 ¹	8.75	13.5	10.75	13	15	20.75	53
B1 _{h9}	5	5	6	10	12	16	20
H1	15	18	24.5	35	43	59	79.5
X DIN5480	-	W16x0.8x 30x18x6m	W22x1.25x 30x16x6m	W32x1.25x 30x24x6m	W40x2x 30x18x6m	W55x2x 30x26x6m	W70x2x 30x34x6m

1. C1~C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.
 2. AF042 ratio 5, 10 offers C3 ≤ 12 option; AF062 ratio 5, 10 offers C3 ≤ 16 option.

Dimensions (2-stage, Ratio $i=12\sim 100$) / AF Series



[unit: mm]

Dimension	AF042	AF060	AF060A	AF075	AF075A	AF100	AF100A	AF140	AF140A	AF180	AF220
D1	50	68		85		120		165		215	250
D2	3.4	5.5		6.8		9		11		13	17
D3 _{j6}	13	16		22		32		40		55	75
D4 _{g6}	35	60		70		90		130		160	180
D5	22	45		60		80		75		95	115
D6	M4x0.7P	M5 x 0.8P		M8 x 1.25P		M12 x 1.75P		M16 x 2P		M20x2.5P	M20x2.5P
D7	56	16		22		32		40		55	75
L1	42	62		76		105		142		180	220
L2	19.5	28.5		36		58		82		82	105
L3	6.5	20		20		30		30		30	33
L4	1	1.5		2		2		3		3	3
L5	16	25		32		40		63		70	90
L6	2	2		3		5		5		6	7
L7	4	6		7		10		12		15	20
L8	58.5	65.5	91.5	119.5	134.5	131	150.5	166.5	181.5	205.5	248
L9	42	60		90		115		142		180	220
L10	10	12.5		19		28		36		42	42
L11	-	26		26		26		40		41.5	52
L12	-	15		15		15		20		21.5	28
L13	-	21		22.5		23		33.5		33.5	45
C1 ³	46	46	70	70	100	100	130	130	165	165	215
C2 ³	M4x0.7P	M4x0.7P	M5 x 0.8P	M5 x 0.8P	M6 x 1P	M6 x 1P	M8x1.25P	M8x1.25P	M10x1.5P	M10x1.5P	M12x1.75P
C3 ³	≤11 / ≤12	≤11 / ≤12	≤14 / ≤16	≤14 / ≤15.875 / ≤16	≤19 / ≤24	≤19 / ≤24	≤32	≤32	≤38	≤38	≤48
C4 ³	25	25	34	34	40	40	50	50	60	60	85
C5 ³	30	30	50	50	80	80	110	110	130	130	180
C6 ³	3.5	3.5	8	8	4	4	5	5	6	6	6
C7 ³	42	42	60	60	90	90	115	115	142	142	190
C8 ³	29.5	29.5	19	19	17	17	19.5	19.5	22.5	22.5	29
C9 ³	114	143.5	159	194.5	207.5	207.5	258	298	316	340	415
C10 ³	8.75	8.75	13.5	13.5	10.75	10.75	13	13	15	15	20.75
B1 _{h9}	5	5		6		10		12		16	20
H1	15	18		24.5		35		43		59	79.5
X DIN5480	-	W16x0.8x 30x18x6m		W22x1.25x 30x16x6m		W32x1.25x 30x24x6m		W40x2x 30x18x6m		W55x2x 30x26x6m	W70x2x 30x34x6m

3. C1~C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.

Specifications / AFR Series

Gearbox Performance

Model No.	Stage	Ratio ^A	AFR042	AFR060	AFR060A	AFR075	AFR075A	AFR100	AFR100A	AFR140	AFR140A	AFR180	AFR220	
Nominal Output Torque T_{2N}	1	3	9	36	-	90	-	195	-	342	-	588	1,140	
		4	12	48	-	120	-	260	-	520	-	1,040	1,680	
		5	15	60	-	150	-	325	-	650	-	1,200	2,000	
		6	18	55	-	150	-	310	-	600	-	1,100	1,900	
		7	19	50	-	140	-	300	-	550	-	1,100	1,800	
		8	17	45	-	120	-	260	-	500	-	1,000	1,600	
		9	14	40	-	100	-	230	-	450	-	900	1,500	
		10	14	60	-	150	-	325	-	650	-	1,200	2,000	
		12	-	55	-	150	-	310	-	600	-	1,100	1,900	
		14	-	42	-	140	-	300	-	550	-	1,100	1,800	
	16	-	45	-	120	-	260	-	500	-	1,000	1,600		
	20	-	40	-	100	-	230	-	450	-	900	1,500		
	2	12	12	-	-	-	-	-	-	-	-	-	-	-
		15	14	-	-	-	-	-	-	-	-	-	-	-
		16	15	-	-	-	-	-	-	-	-	-	-	-
		20	14	-	-	-	-	-	-	-	-	-	-	-
		25	15	60	60	150	150	325	325	650	650	1,200	2,000	
		28	19	50	50	140	140	300	300	550	550	1,100	1,800	
		30	20	55	55	150	150	310	310	600	600	1,100	1,900	
		32	17	45	45	120	120	260	260	500	500	1,000	1,600	
		35	19	50	50	140	140	300	300	550	550	1,100	1,800	
		40	17	45	45	120	120	260	260	500	500	1,000	1,600	
		45	14	40	40	100	100	230	230	450	450	900	1,500	
		48	-	-	55	150	150	310	310	600	600	1,100	1,900	
		50	14	60	60	100	100	230	230	650	650	1,200	2,000	
		60	20	55	55	150	150	310	310	600	600	1,100	1,900	
		64	-	-	45	120	120	260	260	500	500	1,000	1,600	
		70	19	50	50	140	140	300	300	550	550	1,100	1,800	
		80	17	45	45	120	120	260	260	500	500	1,000	1,600	
		90	14	40	40	100	100	230	230	450	450	900	1,500	
		100	14	40	60	150	150	325	325	650	650	1,200	2,000	
		120	-	-	55	150	150	310	310	600	600	1,100	1,900	
140	-	-	50	140	140	300	300	550	550	1,100	1,800			
160	-	-	45	120	120	260	260	500	500	1,000	1,600			
180	-	-	40	100	100	230	230	450	450	900	1,500			
200	-	-	40	100	100	230	230	450	450	900	1,500			
Emergency Stop Torque T_{2NOT} ^B	Nm	1,2	3~200	3 times of Nominal Output Torque										
Nominal Input Speed n_{1N}	rpm	1,2	3~200	5,000	5,000	5,000	4,000	4,000	4,000	4,000	3,000	3,000	3,000	2,000
Max. Input Speed n_{1B}	rpm	1,2	3~200	10,000	10,000	10,000	8,000	8,000	8,000	8,000	6,000	6,000	6,000	4,000
Micro Backlash P0	arcmin	1	3~20	-	-	-	≤2	-	≤2	-	≤2	-	≤2	≤2
		2	12~200	-	-	-	≤4	≤4	≤4	≤4	≤4	≤4	≤4	≤4
Reduced Backlash P1	arcmin	1	3~20	≤4	≤4	-	≤4	-	≤4	-	≤4	-	≤4	≤4
		2	12~200	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7
Standard Backlash P2	arcmin	1	3~20	≤6	≤6	-	≤6	-	≤6	-	≤6	-	≤6	≤6
		2	12~200	≤9	≤9	≤9	≤9	≤9	≤9	≤9	≤9	≤9	≤9	≤9
Torsional Rigidity	Nm/arcmin	1,2	3~200	3	7	7	14	14	25	25	50	50	145	225
Max. Radial Load F_{2RB} ^C	N	1,2	3~200	610	1,400	1,400	4,100	4,100	9,200	9,200	14,000	14,000	18,000	33,000
Max. Axial Load F_{2aB} ^C	N	1,2	3~200	320	1,100	1,100	3,700	3,700	5,800	5,800	11,400	11,400	19,500	16,300
Service Life ^D	hr	1,2	3~200	30,000										
Efficiency η	%	1	3~20	≥95%										
		2	12~200	≥92%										
Weight	kg	1	3~20	0.9	2.1	-	6.4	-	13.9	-	23.7	-	50	83
		2	12~200	1.2	1.5	2.8	7.8	8	15.1	15.1	26.7	29.2	54	95
Operating Temp	°C	1,2	3~200	-10°C~+90°C										
Lubrication		1,2	3~200	Synthetic lubrication oils										
Degree of Gearbox Protection		1,2	3~200	IP65										
Mounting Position		1,2	3~200	all directions										
Noise ($n_1=3000\text{rpm}, i=10, \text{No load}$) ^E	dB(A)	1,2	3~200	≤61	≤63	≤65	≤65	≤68	≤68	≤70	≤70	≤72	≤72	≤74

A. Ratio ($i=N_{in}/N_{out}$)B. Max. acceleration torque $T_{2B} = 60\%$ of T_{2NOT}

C. Applied to the output shaft center at 100 rpm

D. For continuous operation, the service life time is less than 15,000 hrs

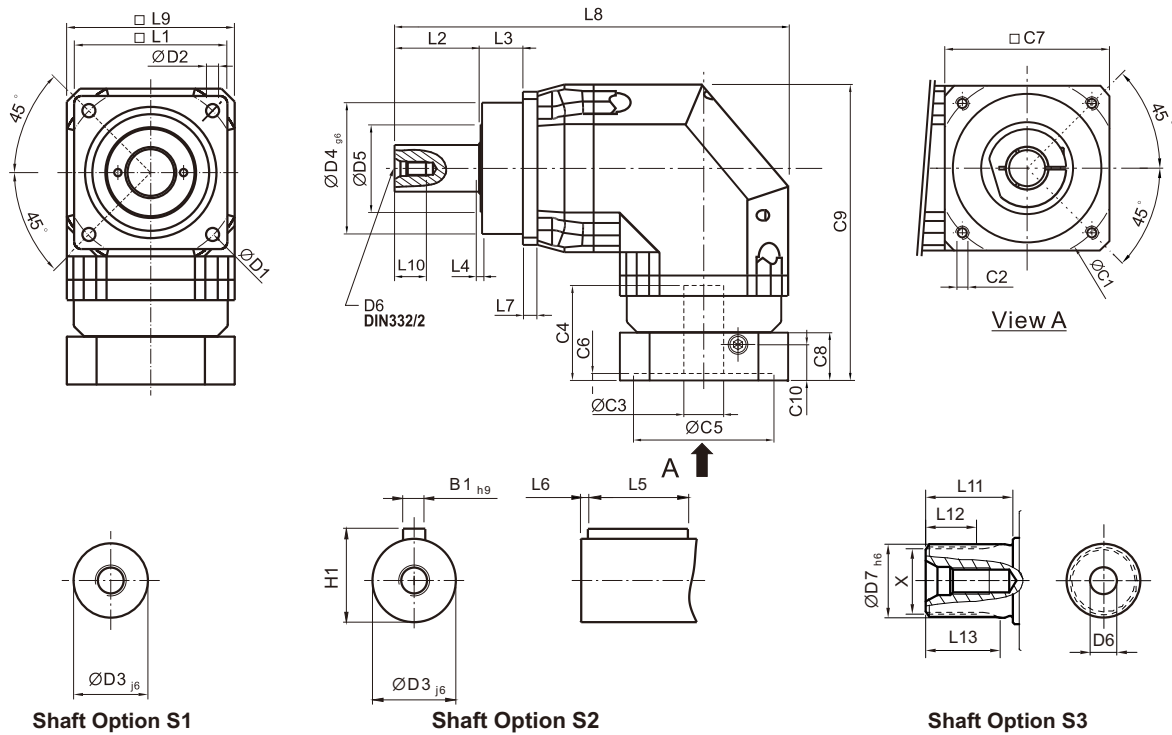
E. These values are measured by gearbox with ratio = 10 (1-stage) or ratio = 100 (2-stage) at 3,000 rpm no loading.

By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher

Gearbox Inertia

Model No.		Stage	Ratio	AFR042	AFR060	AFR060A	AFR075	AFR075A	AFR100	AFR100A	AFR140	AFR140A	AFR180	AFR220	
Mass Moments of Inertia J ₁	kg · cm ²	1	3~10	0.09	0.35	—	2.25	—	6.84	—	23.4	—	68.9	135.4	
			12~20	—	0.07	—	1.87	—	6.25	—	21.8	—	65.6	119.8	
		2	12~20	0.09	—	—	—	—	—	—	—	—	—	—	—
			25~90	0.09	0.09	0.35	0.35	2.25	2.25	6.84	6.84	23.4	23.4	68.9	—
			48, 64	—	—	0.07	0.31	1.87	1.87	6.25	6.25	21.8	21.8	65.6	—
			100~200	—	—	0.07	0.31	1.87	1.87	6.25	6.25	21.8	21.8	65.6	—
			—	—	—	—	—	—	—	—	—	—	—	—	—
—	—	—	—	—	—	—	—	—	—	—	—	—	—		
—	—	—	—	—	—	—	—	—	—	—	—	—	—		

Dimensions (1-stage, Ratio $i=3\sim 20$) / AFR Series

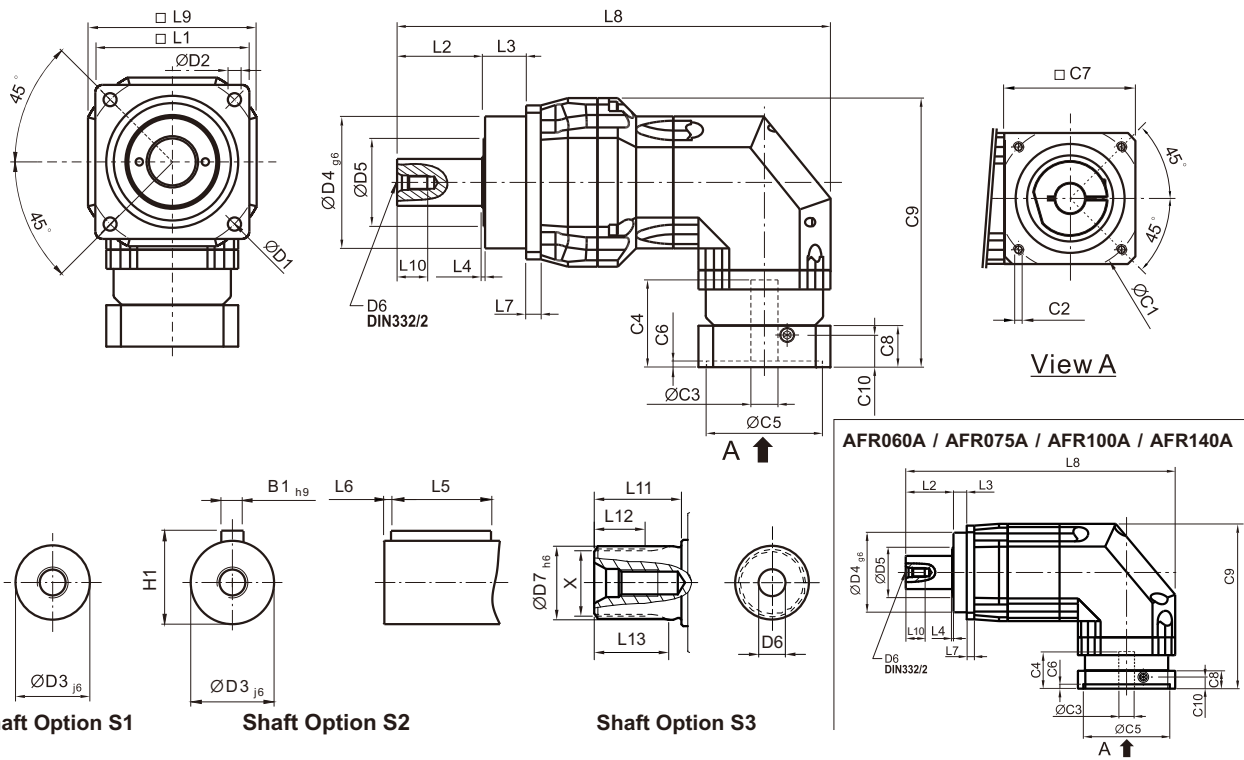


[unit: mm]

Dimension	AFR042	AFR060	AFR075	AFR100	AFR140	AFR180	AFR220
D1	50	68	85	120	165	215	250
D2	3.4	5.5	6.8	9	11	13	17
D3 _{j6}	13	16	22	32	40	55	75
D4 _{g6}	35	60	70	90	130	160	180
D5	22	45	60	80	75	95	115
D6	M4 x 0.7P	M5 x 0.8P	M8 x 1.25P	M12 x 1.75P	M16 x 2P	M20 x 2.5P	M20 x 2.5P
D7 _{h6}	-	16	22	32	40	55	75
L1	42	62	76	105	142	180	220
L2	19.5	28.5	36	58	82	82	105
L3	6.5	20	20	30	30	30	33
L4	1	1.5	2	2	3	3	3
L5	16	25	32	40	63	70	90
L6	2	2	3	5	5	6	7
L7	4	6	7	10	12	15	20
L8	111.5	150	219	269.5	338.5	397	484
L9	42	60	90	115	142	180	220
L10	10	12.5	19	28	36	42	42
L11	-	26	26	26	40	41.5	52
L12	-	15	15	15	20	21.5	28
L13	-	21	22.5	23	33.5	33.5	45
C1 ¹	46	70	100	130	165	215	235
C2 ¹	M4 x 0.7P	M5 x 0.8P	M6 x 1P	M8 x 1.25P	M10 x 1.5P	M12 x 1.75P	M12 x 1.75P
C3 ¹	≤11 / ≤12	≤14 / ≤16	≤19 / ≤24	≤32	≤38	≤48	≤55
C4 ¹	25	34	40	50	60	85	116
C5 ¹	30	50	80	110	130	180	200
C6 ¹	3.5	8	4	5	6	6	6
C7 ¹	42	60	90	115	142	190	220
C8 ¹	29.5	19	17	19.5	22.5	29	63
C9 ¹	90.5	111.5	152.5	191.5	235.5	303.5	378.5
C10 ¹	8.75	13.5	10.75	13	15	20.75	53
B1 _{h9}	5	5	6	10	12	16	20
H1	15	18	24.5	35	43	59	79.5
X DIN5480	-	W16x0.8x 30x18x6m	W22x1.25x 30x16x6m	W32x1.25x 30x24x6m	W40x2x 30x18x6m	W55x2x 30x26x6m	W70x2x 30x34x6m

1. C1-C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.

Dimensions (2-stage, Ratio $i=12\sim 200$) / AFR Series

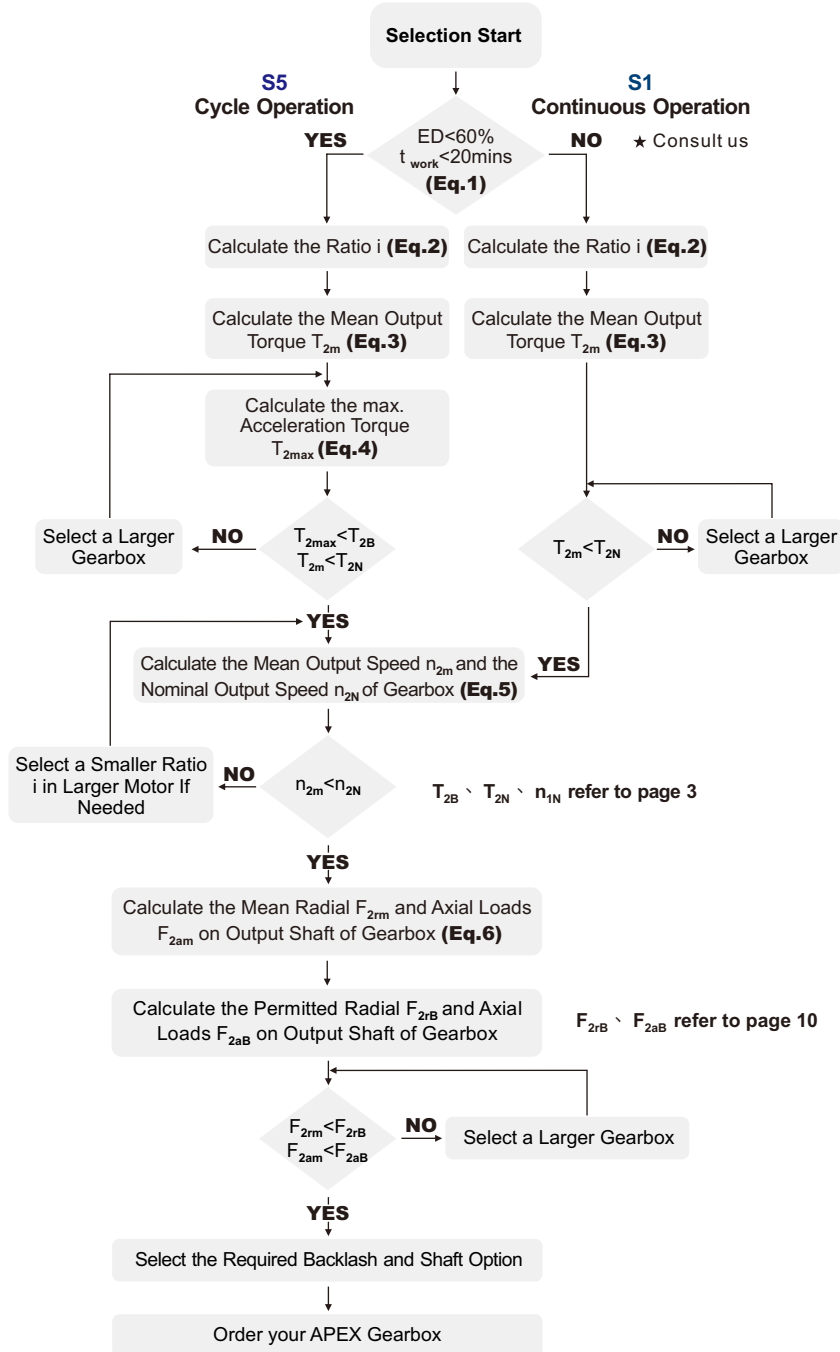


[unit: mm]

Dimension	AFR042	AFR060	AFR060A	AFR075	AFR075A	AFR100	AFR100A	AFR140	AFR140A	AFR180	AFR220
D1	50	68		85		120		165		215	250
D2	3.4	5.5		6.8		9		11		13	17
D3 _{j6}	13	16		22		32		40		55	75
D4 _{g6}	35	60		70		90		130		160	180
D5	22	45		60		80		75		95	115
D6	M4x0.7P	M5 x 0.8P		M8 x 1.25P		M12 x 1.75P		M16 x 2P		M20x2.5P	M20x2.5P
D7	-	16		22		32		40		55	75
L1	42	62		76		105		142		180	220
L2	19.5	28.5		36		58		82		82	105
L3	6.5	20		20		30		30		30	33
L4	1	1.5		2		2		3		3	3
L5	16	25		32		40		63		70	90
L6	2	2		3		5		5		6	7
L7	4	6		7		10		12		15	20
L8	139	168.5	187	222.5	267	295.5	330.5	370.5	410	434	521
L9	42	60		90		115		142		180	220
L10	10	12.5		19		28		36		42	42
L11	-	26		26		26		40		41.5	52
L12	-	15		15		15		20		21.5	28
L13	-	21		22.5		23		33.5		33.5	45
C1 ²	46	46	70	70	100	100	130	130	165	165	215
C2 ²	M4x0.7P	M4x0.7P	M5 x 0.8P	M5 x 0.8P	M6 x 1P	M6 x 1P	M8x1.25P	M8x1.25P	M10x1.5P	M10x1.5P	M12x1.75P
C3 ²	≤11 / ≤12	≤11 / ≤12	≤14 / ≤16	≤14 / ≤15.875 / ≤16	≤19 / ≤24	≤19 / ≤24	≤32	≤32	≤38	≤38	≤48
C4 ²	25	25	34	34	40	40	50	50	60	60	85
C5 ²	30	30	50	50	80	80	110	110	130	130	180
C6 ²	3.5	3.5	8	8	4	4	5	5	6	6	6
C7 ²	42	42	60	60	90	90	115	115	142	142	190
C8 ²	29.5	29.5	19	19	17	17	19.5	19.5	22.5	22.5	29
C9 ²	90.5	99.5	111.5	126.5	152.5	165	191.5	205	235.5	254.5	323.5
C10 ²	8.75	8.75	13.5	13.5	10.75	10.75	13	13	15	15	20.75
B1 _{h9}	5	5		6		10		12		16	20
H1	15	18		24.5		35		43		59	79.5
X DIN5480	-	W16x0.8x 30x18x6m		W22x1.25x 30x16x6m		W32x1.25x 30x24x6m		W40x2x 30x18x6m		W55x2x 30x26x6m	W70x2x 30x34x6m

2. C1~C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.

Selection of the Optimum Gearbox



Recommended (for S5 Cycle Operation)

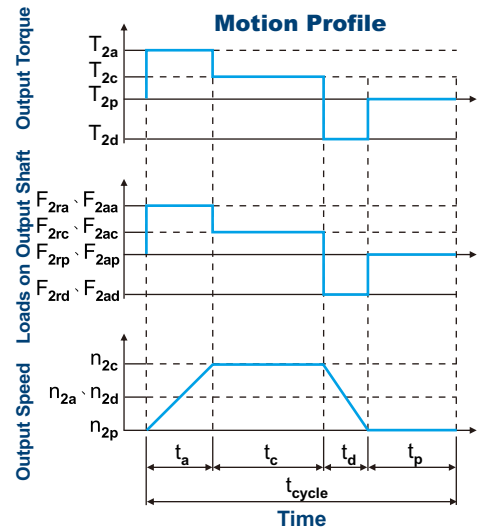
The general design is given for

$$\frac{J_L}{i^2} \leq 4 \times J_m$$

The optimal design is given for

$$\frac{J_L}{i^2} \cong J_m$$

J_L Load Inertia
 J_m Motor Inertia



$$1. ED = \frac{t_a + t_c + t_d}{t_{cycle}} \times 100\%, t_{work} = t_a + t_c + t_d$$

Index : a. Acceleration, c. Constant, d. Deceleration, p. Pause (Eq.1)

$$2. i \cong \frac{n_m}{n_{work}}$$

n_m Output Speed of the Motor
 n_{work} Working Speed (Eq.2)

$$3. T_{2m} = \sqrt[3]{\frac{n_{2a} \times t_a \times T_{2a}^3 + n_{2c} \times t_c \times T_{2c}^3 + n_{2d} \times t_d \times T_{2d}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$

(Eq.3)

$$4. T_{2max} = T_{mB} \times i \times k_s \times \eta$$

where K_s is

K_s	No. of Cycles / hr
1.0	0 ~ 1,000
1.1	1,000 ~ 1,500
1.3	1,500 ~ 2,000
1.6	2,000 ~ 3,000
1.8	3,000 ~ 5,000

T_{mB} Max. Output Torque of the Motor
 η Efficiency of the Gearbox (Eq.4)

$$5. n_{2a} = n_{2d} = \frac{1}{2} \times n_{2c}$$

$$n_{2m} = \frac{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}{t_a + t_c + t_d}$$

$$n_{2N} = \frac{n_{1N}}{i}$$

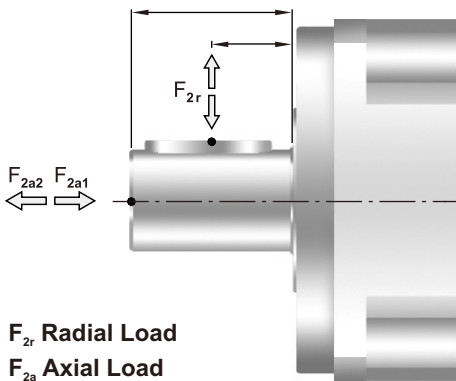
(Eq.5)

$$6. F_{2rm} = \sqrt[3]{\frac{n_{2a} \times t_a \times F_{2ra}^3 + n_{2c} \times t_c \times F_{2rc}^3 + n_{2d} \times t_d \times F_{2rd}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$

$$F_{2am} = \sqrt[3]{\frac{n_{2a} \times t_a \times F_{2aa}^3 + n_{2c} \times t_c \times F_{2ac}^3 + n_{2d} \times t_d \times F_{2ad}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$

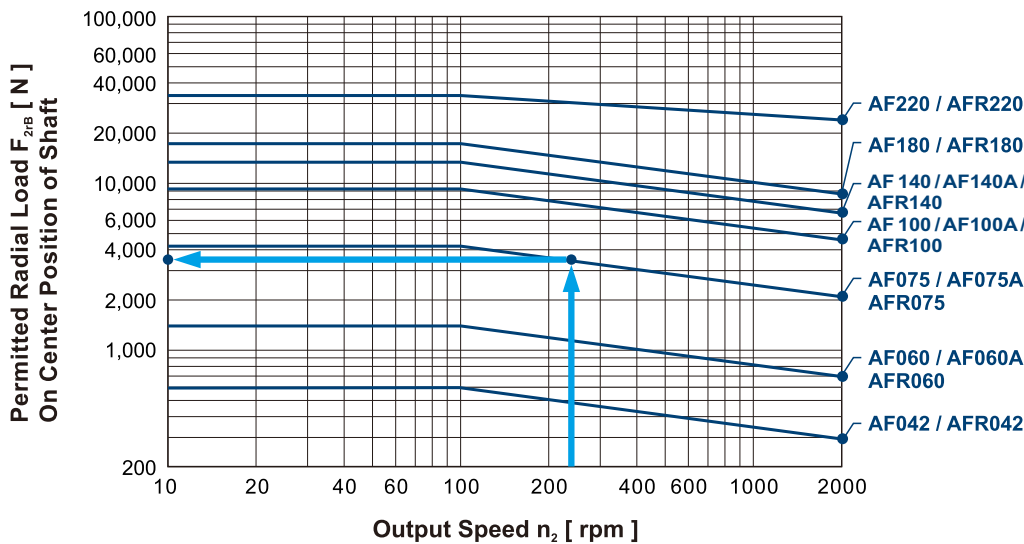
(Eq.6)

Permitted Radial and Axial Loads

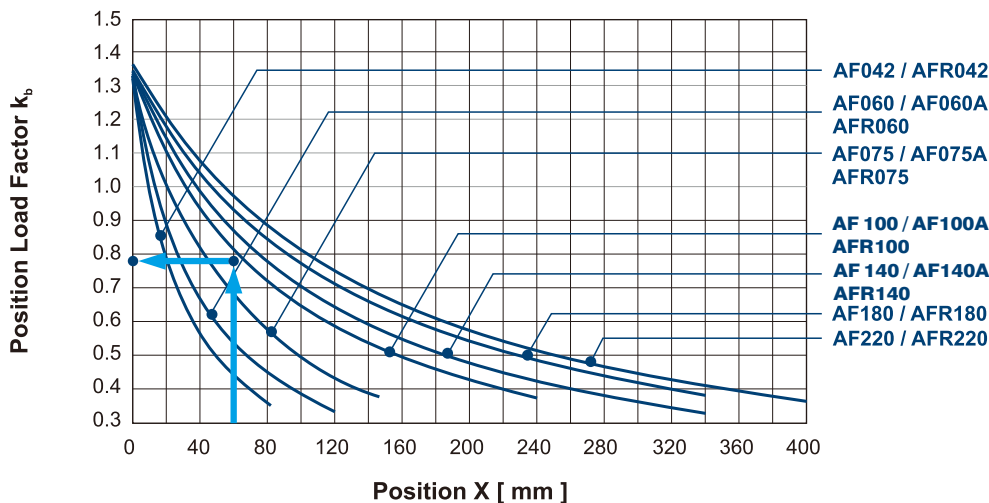


The permitted radial and axial loads on output shaft of the gearbox depend on the design of the gearbox supporting bearings. APEX use the extension straddle oversized ball bearing design. It can take heavy load from both axes.

F_{2r} Radial Load
 F_{2a} Axial Load



If radial force F_{2r} is exerted on the center of the output shaft $X=1/2 \times L$. Under various operating condition the lifetime is over 30,000 hours.* The permitted radial load is given on left diagram.



If radial force F_{2r} is not exerted on the center of the output shaft $X < 1/2 \times L$ or $X > 1/2 \times L$. The permitted radial and axial loads can be calculated by the position load factor k_b on the left diagram.

* S1 service life 15,000 hrs



**APEX TAIWAN NORTH
ANDTEK AUTOMATION CO.,LTD**
TEL +886-02-82262655
13F-5, No.2, Jian 8th Rd., Jhonghe Dist., New
Taipei City 235, TAIWAN
sales@andtek.com.tw
www.apexdyna.com



**APEX TAIWAN CENTRAL
ANDTEK AUTOMATION CO.,LTD**
TEL +886-04-23594286
9F-6, No.925, Sec.4, Taiwan Blvd., Xitun Dist.
Taichung City 407 TAIWAN
sales@andtek.com.tw
www.apexdyna.com



**APEX TAIWAN SOUTH
MEN JENN ELECTRIC CO., LTD.**
TEL +886-06-2337332 ~ 6
No.774, Zhonghua Rd., Yongkang Dist., Tainan
City 710, TAIWAN
menjenn@ms24.hinet.net
www.apexdyna.com



APEX DYNAMICS INC. SHANGHAI
TEL +86-21-69220577
No.128 ZHUYING Road QINGPU Industry Area,
Shanghai, CHINA
sales@apexdyna.cn
www.apexdyna.cn



APEX DYNAMICS SHENZHEN, LTD.
TEL +86-755-84516325
No. 1102A of D area , CFG mansion ,Bao Yuan
Road, Bao'an District, Shenzhen ,CHINA.
sales@szapexdyna.com
www.szapexdyna.com



APEX DYNAMICS BEIJING, LTD.
TEL +86-10-69570691
NO.1,YaoPingRoad,SongZhuang Town, Tongzhou
istrict, Beijing, CHINA.
bjapexdyna@163.com
www.bjapex.cn



CHONGQING APEX DYNAMICS CO., LTD.
TEL +86-23-67686860
406, Building 5, No.68,Jinyu Avenue, Beibu New
Area, Chongqing, CHINA
sales@cqapexdyna.com
www.apexdyna.com



APEX (XIAMEN) DYNAMICS TECHNOLOGY CO., LTD.
TEL +86-0592-720-5279
Unit B-3,1F.,No.129,Jingquan Road, Jimei District,
Xiamen, Fujian, CHINA
sales@xmapexdyna.com
www.xmapexdyna.com



APEX DYNAMICS USA, INC.
TEL +1-631-2449040
885 Marconi Avenue Ronkonkoma, NY 11779
U.S.A.
sales@apexdynamicsusa.com
www.apexdynamicsusa.com



APEX DYNAMICS KOREA
TEL +82-31-8179992
1246-32, Seongsuk-dong, Ilsandong-gu, Goyang-city,
Gyeonggi-Do, KOREA (R.O.K) 410-570
sales@apexdynakorea.co.kr
www.apexdynakorea.co.kr



APEX DYNAMICS JAPAN
TEL +81-092-4511202
1-13-3, Sannou, Hakata-ku, Fukuoka-Shi 812-0015,
JAPAN
sales@apexdyna.jp
www.apexdyna.jp



APEX DYNAMICS SINGAPORE PTE LTD
TEL +65-62-626228
3 South Buona Vista Road, #05-15 & #06-15.
SINGAPORE 118136
sales@apexdyna.com.sg
www.apexdyna.com.sg



APEX DYNAMICS (THAILAND) CO., LTD.
TEL +66-2-3266233
73 Soi Ladkrabang 30, Kadkrabang Rd.,Bangkok
10520, THAILAND
sales@apexdyna.co.th
www.apexdyna.co.th



APEX DYNAMICS BV
TEL +31-492-509995
Churchillaan 101 5705 BK Helmond, NETHERLANDS
sales@apexdyna.nl
www.apexdyna.nl



**APEX DYNAMICS
POLSKA SP. Z O.O.**
TEL +48-12-6304728
Krakowska 50, 32-083 Balice, POLAND
sales@apexdyna.pl
www.apexdyna.pl



APEX DYNAMICS SPAIN, S.L.
TEL +34-93-6562990
Poligono Industrial Moli dels Freres, Calle Cnº
3 South Buona Vista Road, #05-15 & #06-15.
SINGAPORE 118136
sales@apexdyna.com.sg
www.apexdyna.com.sg



APEX DYNAMICS IRAN.
TEL +98-21-66593517
APT#6, 3rd Flr, No.5, 3rd Kowsar St., Sattarkhan
Ave., Tehran, IRAN
alahyari@farasvco.com
www.apexdyna.ir



APEKS REDUKTOR VE DISLI SAN. TIC. LTD. STI.
TEL +90-232-4589960
10042 Sok.No:10 AOSB Çiğli-Izmir, TURKEY
sales@apexdyna.com.tr
www.apexdyna.com.tr



APEX DYNAMICS AUSTRALIA PTY LTD.
TEL +613-95-852739
36 Taunton Drive, Cheltenham, Victoria 3192
AUSTRALIA.
sales@apexdyna.com.au
www.apexdyna.com.au



APEX DYNAMICS (I) JV
TEL +91-80-55345541
GAT NO. 279, KHED SHIVAPUR BAUG, TALUKA
HAVELI PUNE - 412205 INDIA.
sales@apexdyna.co.in
www.apexdyna.co.in



APEX DYNAMICS FRANCE SAS
TEL +33-160-135097
11 - Burospace F - 91570 -
Bièvres, FRANCE
info@apexdyna.fr
www.apexdyna.fr



APEX DYNAMICS SWEDEN AB
TEL +46-75-242444
Fredrikbergsgatan 2 SE-573 92 Tranås, SWEDEN
sales@apexdyna.se
www.apexdyna.se



PT.APEX DYNAMICS INDONESIA
TEL +62 21 2928 3681
Rukan Aralia Blok HY43 no.11, Harapan Indah II,
Bekasi - Jawa Barat, INDONESIA 17214
sales@apexdyna.co.id
www.apexdyna.co.id



APEX DYNAMICS GERMANY GMBH
TEL +49-7181-9329955
Spanninger Str. 9, 73650 Winterbach, GERMANY
Langer@apexdynamics.de
www.apexdynamics.de



APEX DYNAMICS CZECH S.R.O.
TEL +420-577-663877
tř. Tomáše Bati 1851 765 02 Otrokovice ČESKÁ
REPUBLIKA
info@apexdynaczech.cz
www.apexdynaczech.cz



APEX DYNAMICS РОССИЯ
TEL +7-495-2255452
+7-495-6462422
г.Москва, ул. Южнопортовая, дом 7, строение
"С", 3-й этаж
info@apexdynarussia.ru
www.apexdynarussia.ru



APEX DYNAMICS UK LIMITED
TEL +44-1827-253340
2 Centurion Way, Centurion Park, Tamworth
Staffs, B77 5PN, UK
sales@apexdynamicsuk.com
www.apexdynamicsuk.com



APEX DYNAMICS SWITZERLAND AG
TEL +41-55-4517020 Talstrasse 24, CH-8852
Altendorf, SWITZERLAND
info@apexdyna.ch
www.apexdyna.ch



APEX DYNAMICS MOTION SDN BHD
TEL +60 7237 1055
No.1, Jalan Perniagaan Setia 3, Taman
Perniagaan Setia, 81100 Johor Bahru, Johor,
MALAYSIA (Setia Business Park 2 @ Iskandar
Malaysia)
sales@apexdyna.com.sg
www.apexdyna.com.sg



APEX DYNAMICS BRAZIL
TEL +55-47-30298700
Rua Senador Petrônio Portela, 47 - Bloco 5, Zona
Industrial Norte - CEP 89218-575 - Joinville (SC)
lucan@neoyama.com.br
adriano.duarte@neoyama.com.br
www.neoyama.com.br



APEX DYNAMICS ITALY
TEL +39 02.36634521
VIA E. DE AMICIS, 2 – 20091 BRESSO (MI)
info@apexdynamics.it
www.apexdynamics.it



APEX DYNAMICS, INC.

No. 10, Keyuan 3rd Rd., Situn District, Taichung City 40763, Taiwan (R.O.C.)
Tel:886-4-24650219 | Fax:886-4-24650118
sales@apexdyna.com | http://www.apexdyna.com

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